

**Directions:**

Answer four questions well, two from part 1 and two from part 2 (you may answer all questions but only the best 2 scores from each part will be used). Show your work. All proofs must be in Statement/Reason format except showing a set is/is not a subspace/linearly independent/spans  $W$ . You may use your pre-approved theorem list and may cite any correct result on it unless explicitly disallowed by the question. All answers must be justified by computation or explanation. You may use a calculator, and no work is required for reduction to reduced row echelon form (RREF) or for real arithmetic. For all other computations you must show work that justifies the answer without a calculator or be able to do it in your head.

## PART 1

1. Determine whether the given subset  $W$  is a subspace of  $\mathbf{R}^3$  (and show your answer is correct).

$$\text{a) } W = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \mid x+y=0 \right\}$$

$$\text{b) } W = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \mid xy=0 \right\}$$

2. Find a basis for the vector space  $V$ .

$$\text{a) } V = \{[r-s+t, r-s, r-s-t] : r, s, t, \in \mathbf{R}\} \quad \text{b) } V = \{p \in P_2 : p(1) = 0\}$$

3. a) Find the eigenvalues of  $A = \begin{bmatrix} 2 & 3 \\ -1 & 6 \end{bmatrix}$ . For each eigenvalue, find an eigenvector.

$$\text{b) Let } \det \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} = -5. \quad \text{Compute } \det \begin{bmatrix} 8g & 8h & 8i \\ d+a & e+b & f+c \\ a & b & c \end{bmatrix}$$

## PART 2

4. Let  $A$  be a nonsingular matrix and suppose  $\lambda$  is an eigenvalue of  $A$ . Prove  $\frac{1}{\lambda}$  is an eigenvalue of  $A^{-1}$ .

5. Prove H19: Let  $A_1, \dots, A_k$  be  $n \times n$  matrices.  $\det(A_1 \dots A_k) = \det A_1 \dots \det A_k$ . (do NOT cite H19 for this problem).

6. Let  $V$  be a vector space and  $\mathbf{v}$ ,  $\mathbf{w}$ , and  $\mathbf{z}$  let be vectors in  $V$ . Prove that if a vector  $\mathbf{x}$  is a linear combination of  $\mathbf{v}$  and  $\mathbf{w}$  then  $\mathbf{x}$  is a linear combination of  $\mathbf{v}$ ,  $\mathbf{w}$ , and  $\mathbf{z}$ . (do NOT cite Theorem 4.6 for this problem).

