

Mixed Model Analysis

Basic model:

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\mathbf{u} + \mathbf{e}$$

where

\mathbf{X} is a $n \times p$ model matrix of known constants

$\boldsymbol{\beta}$ is a $p \times 1$ vector of “fixed” unknown parameter values

\mathbf{Z} is a $n \times q$ model matrix of known constants

\mathbf{u} is a $q \times 1$ random vector

\mathbf{e} is a $n \times 1$ vector of random errors

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with

$$E(\mathbf{e}) = \mathbf{0} \quad \text{Var}(\mathbf{e}) = \mathbf{R}$$

$$E(\mathbf{u}) = \mathbf{0} \quad \text{Var}(\mathbf{u}) = \mathbf{G}$$

$$\text{Cov}(\mathbf{e}, \mathbf{u}) = \mathbf{0}$$

Then

$$\begin{aligned} E(\mathbf{Y}) &= E(\mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\mathbf{u} + \mathbf{e}) \\ &= \mathbf{X}\boldsymbol{\beta} + \mathbf{Z}E(\mathbf{u}) + E(\mathbf{e}) \\ &= \mathbf{X}\boldsymbol{\beta} \end{aligned}$$

$$\begin{aligned} \text{Var}(\mathbf{Y}) &= \text{Var}(\mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\mathbf{u} + \mathbf{e}) \\ &= \text{Var}(\mathbf{Z}\mathbf{u}) + \text{Var}(\mathbf{e}) \\ &= \mathbf{Z}\mathbf{G}\mathbf{Z}^T + \mathbf{R} \\ &\equiv \Sigma \end{aligned}$$

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Normal-theory mixed model

$$\begin{bmatrix} \mathbf{u} \\ \mathbf{e} \end{bmatrix} \sim N\left(\begin{bmatrix} \mathbf{0} \\ \mathbf{0} \end{bmatrix}, \begin{bmatrix} \mathbf{G} & \mathbf{0} \\ \mathbf{0} & \mathbf{R} \end{bmatrix}\right)$$

Then,

$$\mathbf{Y} \sim N(\mathbf{X}\boldsymbol{\beta}, \underline{\mathbf{Z}\mathbf{G}\mathbf{Z}^T + \mathbf{R}})$$

↑
call this Σ

Example 10.1: Random Blocks

Comparison of four processes for producing penicillin

$\begin{array}{c} \text{Process A} \\ \text{Process B} \\ \text{Process C} \\ \text{Process D} \end{array} \Bigg\}$ Levels of a “fixed” treatment factor

Blocks correspond to different batches of an important raw material, corn steep liquor

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- Random sample of five batches
- Split each batch into four parts:
 - run each process on one part
 - randomize the order in which the processes are run within each batch

Here, batch effects are considered as *random block effects*:

- Batches are sampled from a population of many possible batches
- To repeat this experiment you would need to use a different set of batches of raw material

Data Source: Box, Hunter & Hunter (1978), *Statistics for Experimenters*, Wiley & Sons, New York.

Data file: penclln.dat
SAS code: penclln.sas
S-PLUS code: penclln.ssc

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Model:

$$Y_{ij} = \mu + \alpha_i + \beta_j + e_{ij}$$

↑ ↑ ↑ ↑
 Yield mean random random
 for the yield batch error
 i-th process for the effect
 applied i-th process,
 to the averaging
 j-th batch across the
 entire
 population
 of
 possible
 batches

where

$$\begin{aligned}\beta_j &\sim NID(0, \sigma_\beta^2) \\ e_{ij} &\sim NID(0, \sigma_e^2)\end{aligned}$$

and any e_{ij} is independent of any β_j .

Here

$$\begin{aligned}\mu_i = E(Y_{ij}) &= E(\mu + \alpha_i + \beta_j + e_{ij}) \\ &= \mu + \alpha_i + E(\beta_j) + E(e_{ij}) \\ &= \mu + \alpha_i \quad i = 1, 2, 3, 4\end{aligned}$$

represents the mean yield for the i -th process, averaging across all possible batches.

PROC GLM and PROC MIXED in SAS fit a restricted model with $\alpha_4 = 0$. Then

- $\mu = \mu_4$ is the mean yield for process D
- $\alpha_i = \mu_i - \mu_4 \quad i = 1, 2, 3, 4$.

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In S-PLUS you could use the "treatment" constraints where $\alpha_1 = 0$. Then

- $\mu = \mu_1$ is the mean yield for process A
- $\alpha_i = \mu_i - \mu_1 \quad i = 1, 2, 3, 4$.

Alternatively, you could choose the solution to the normal equations given by "sum" constraints

- $\alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 = 0$
- $\mu = (\mu_1 + \mu_2 + \mu_3 + \mu_4)/4$
- $\alpha_i = \mu_i - \mu$

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Variance-covariance structure:

$$\begin{aligned} \text{Var}(Y_{ij}) &= \text{Var}(\mu + \alpha_i + \beta_j + e_{ij}) \\ &= \text{Var}(\beta_j + e_{ij}) \\ &= \text{Var}(\beta_j) + \text{Var}(e_{ij}) \\ &= \sigma_\beta^2 + \sigma_e^2 \quad \text{for all } (i, j) \end{aligned}$$

Different runs on the same batch:

$$\begin{aligned} \text{Cov}(Y_{ij}, Y_{kj}) &= \text{Cov}(\mu + \alpha_i + \beta_j + e_{ij}, \mu + \alpha_k + \beta_j + e_{kj}) \\ &= \text{Cov}(\beta_j + e_{ij}, \beta_j + e_{kj}) \\ &= \text{Cov}(\beta_j, \beta_j) + \text{Cov}(\beta_j, e_{kj}) + \text{Cov}(e_{ij}, \beta_j) \\ &\quad + \text{Cov}(e_{ij}, e_{kj}) \\ &= \text{Var}(\beta_j) \\ &= \sigma_\beta^2 \quad \text{for all } i \neq k \end{aligned}$$

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Correlation among yields for runs on the same batch:

$$\begin{aligned} \rho &= \frac{\text{Cov}(Y_{ij}, Y_{kj})}{\sqrt{\text{Var}(Y_{ij})\text{Var}(Y_{kj})}} \\ &= \frac{\sigma_\beta^2}{\sigma_\beta^2 + \sigma_e^2} \quad \text{for } i \neq k \end{aligned}$$

Results for runs on different batches are uncorrelated (independent):

$$\text{Cov}(Y_{ij}, Y_{k\ell}) = 0 \quad \text{for } j \neq \ell$$

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Results from the four runs on a single batch:

$$\begin{aligned} \text{Var} \begin{bmatrix} Y_{1j} \\ Y_{2j} \\ Y_{3j} \\ Y_{4j} \end{bmatrix} &= \begin{bmatrix} \sigma_\beta^2 + \sigma_e^2 & \sigma_\beta^2 & \sigma_\beta^2 & \sigma_\beta^2 \\ \sigma_\beta^2 & \sigma_\beta^2 + \sigma_e^2 & \sigma_\beta^2 & \sigma_\beta^2 \\ \sigma_\beta^2 & \sigma_\beta^2 & \sigma_\beta^2 + \sigma_e^2 & \sigma_\beta^2 \\ \sigma_\beta^2 & \sigma_\beta^2 & \sigma_\beta^2 & \sigma_\beta^2 + \sigma_e^2 \end{bmatrix} \\ &= \sigma_\beta^2 J + \sigma_e^2 I \\ &\quad \uparrow \quad \uparrow \\ &\quad \text{matrix} \quad \text{identity} \\ &\quad \text{of} \quad \text{matrix} \\ &\quad \text{ones} \end{aligned}$$

This special type of covariance structure is called

compound symmetry

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Write this model as $\mathbf{Y} = \mathbf{X}\beta + \mathbf{Z}\mathbf{u} + \mathbf{e}$

$$\begin{bmatrix} Y_{11} \\ Y_{21} \\ Y_{31} \\ Y_{41} \\ Y_{12} \\ Y_{22} \\ Y_{32} \\ Y_{42} \\ Y_{13} \\ Y_{23} \\ Y_{33} \\ Y_{43} \\ Y_{14} \\ Y_{24} \\ Y_{34} \\ Y_{44} \\ Y_{15} \\ Y_{25} \\ Y_{35} \\ Y_{45} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \\ 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \\ 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \\ 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \mu \\ \alpha_1 \\ \alpha_2 \\ \alpha_3 \\ \alpha_4 \end{bmatrix}$$

$$+ \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \\ \beta_4 \\ \beta_5 \end{bmatrix} + \begin{bmatrix} e_{11} \\ e_{21} \\ e_{31} \\ e_{41} \\ e_{12} \\ e_{22} \\ e_{32} \\ e_{42} \\ e_{13} \\ e_{23} \\ e_{33} \\ e_{43} \\ e_{14} \\ e_{24} \\ e_{34} \\ e_{44} \\ e_{15} \\ e_{25} \\ e_{35} \\ e_{45} \end{bmatrix}$$

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Here

$$G = Var(\mathbf{u}) = \sigma_B^2 I_{5 \times 5}$$

$$R = Var(\mathbf{e}) = \sigma_e^2 I_{n \times n}$$

and

$$Var(\mathbf{Y}) = Var(\mathbf{X}\beta + \mathbf{Z}\mathbf{u} + \mathbf{e})$$

$$= Var(\mathbf{Z}\mathbf{u}) + Var(\mathbf{e})$$

$$= \mathbf{Z}G\mathbf{Z}^T + R$$

$$= \sigma_B^2 \mathbf{Z} \mathbf{Z}^T + \sigma_e^2 I$$

=

$$\begin{bmatrix} \sigma_B^2 J + \sigma_e^2 I & & & \\ & \sigma_B^2 J + \sigma_e^2 I & & \\ & & \ddots & \\ & & & \sigma_B^2 J + \sigma_e^2 I \end{bmatrix}$$

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Example 10.2: Hierarchical Random Effects Model

Analysis of sources of variation in a process used to monitor the production of a pigment paste.

Current Procedure:

- Sample barrels of pigment paste
- One sample from each barrel
- Send the sample to a lab for determination of moisture content

Measured Response: (Y) moisture content of the pigment paste (units of one tenth of 1%).

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Problem: Variation in moisture content is too large

- average moisture content is approximately 25 (or 2.5%)
- standard deviation of about 6

Examine sources of variation:

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Data Collection: Hierarchical
(or nested) Study Design

- Sample b barrels of pigment paste
- s samples are taken from the content of each barrel
- Each sample is mixed and divided into r parts.
Each part is sent to the lab.

There are

$n = (b)(s)(r)$ observations.

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Model:

$$Y_{ijk} = \mu + \beta_i + \delta_{ij} + e_{ijk}$$

where

Y_{ijk} is the moisture content determination for the k -th part of the j -th sample from the i -th barrel
 μ is the mean moisture content

β_i is a random barrel effect:

$$\beta_i \sim NID(0, \sigma_\beta^2)$$

δ_{ij} is a random sample effect:

$$\delta_{ij} \sim NID(0, \sigma_\delta^2)$$

e_{ijk} corresponds to random measurement error:

$$e_{ijk} \sim NID(0, \sigma_e^2)$$

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Covariance Structure

Homogeneous variances:

$$\begin{aligned} Var(Y_{ijk}) &= Var(\mu + \beta_i + \delta_{ij} + e_{ijk}) \\ &= Var(\beta_i) + Var(\delta_{ij}) + Var(e_{ijk}) \\ &= \sigma_\beta^2 + \sigma_\delta^2 + \sigma_e^2 \end{aligned}$$

Two parts of one sample:

$$\begin{aligned} Cov(Y_{ijk}, Y_{ij\ell}) &= Cov(\mu + \beta_i + \delta_{ij} + e_{ijk}, \mu + \beta_i + \delta_{ij} + e_{ij\ell}) \\ &= Cov(\beta_i, \beta_i) + Cov(\delta_{ij}, \delta_{ij}) \\ &= \sigma_\beta^2 + \sigma_\delta^2 \quad \text{for } k \neq \ell \end{aligned}$$

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Observations on different samples taken from the same barrel:

$$\begin{aligned} Cov(Y_{ijk}, Y_{im\ell}) &= Cov(\mu + \beta_i + \delta_{ij} + e_{ijk}, \mu + \beta_i + \delta_{im} + e_{im\ell}) \\ &= Cov(\beta_i, \beta_i) \\ &= \sigma_\beta^2 \quad j \neq m \end{aligned}$$

Observations from different barrels:

$$Cov(Y_{ijk}, Y_{cm\ell}) = 0, \quad i \neq c$$

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Write this model in the form:

$$Y = X\beta + Zu + e$$

In this study

$b = 15$ barrels were sampled

$s = 2$ samples were taken from each barrel

$r = 2$ sub-samples were analyzed from each sample taken from each barrel

Data file: pigment.dat

SAS code: pigment.sas

S-PLUS code: pigment.ssc

$$\begin{bmatrix} Y_{111} \\ Y_{112} \\ Y_{121} \\ Y_{122} \\ Y_{211} \\ Y_{212} \\ Y_{221} \\ Y_{222} \\ \vdots \\ Y_{15,1,1} \\ Y_{15,1,2} \\ Y_{15,2,1} \\ Y_{15,2,2} \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ \vdots \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} [\mu] +$$

$$\begin{bmatrix} 1 & 0 & \dots & 0 & 1 & 0 & 0 & 0 & \dots & 0 & 0 \\ 1 & 0 & \dots & 0 & 1 & 0 & 0 & 0 & \dots & 0 & 0 \\ 1 & 0 & \dots & 0 & 0 & 1 & 0 & 0 & \dots & 0 & 0 \\ 1 & 0 & \dots & 0 & 0 & 1 & 0 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 & 0 & 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 & 0 & 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 & 0 & 0 & 1 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 & 0 & 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots \\ 0 & 0 & \dots & 1 & 0 & 0 & 0 & 0 & \dots & 1 & 0 \\ 0 & 0 & \dots & 1 & 0 & 0 & 0 & 0 & \dots & 1 & 0 \\ 0 & 0 & \dots & 1 & 0 & 0 & 0 & 0 & \dots & 0 & 1 \\ 0 & 0 & \dots & 1 & 0 & 0 & 0 & 0 & \dots & 0 & 1 \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_{15} \\ \delta_{1,1} \\ \delta_{1,2} \\ \delta_{2,1} \\ \delta_{2,2} \\ \vdots \\ \delta_{15,1} \\ \delta_{15,2} \end{bmatrix} + e$$

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where

$$R = Var(e) = \sigma_e^2 I$$

$$G = Var(u) = \begin{bmatrix} \sigma_\beta^2 I & 0 \\ 0 & \sigma_\delta^2 I \end{bmatrix}$$

Then

$$E(Y) = X\beta = 1\mu$$

$$Var(Y) = \Sigma$$

$$= ZGZ^T + R$$

$$= Z \begin{bmatrix} \sigma_\beta^2 I_b & 0 \\ 0 & \sigma_\delta^2 I_{bs} \end{bmatrix} Z^T + \sigma_e^2 I_{bsr}$$

$$= \sigma_\beta^2 (I_b \otimes J_{sr}) + \sigma_\delta^2 (I_{bs} \otimes J_r) + \sigma_e^2 I_{bsr}$$

$$\text{because } Z = [I_b \otimes 1_{sr} | I_{bs} \otimes 1_r]$$

\nearrow
 $(sr) \times 1$
vector
of ones

\nearrow
 $r \times 1$
vector
of ones

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Analysis of Mixed Linear Models

$$Y = X\beta + Zu + e$$

where $X_{n \times p}$ and $Z_{n \times q}$ are known model matrices and

$$\begin{bmatrix} u \\ e \end{bmatrix} \sim N \left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} G & 0 \\ 0 & R \end{bmatrix} \right)$$

Then

$$Y \sim N(X\beta, \Sigma)$$

where

$$\Sigma = ZGZ^T + R$$

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Some objectives

- (i) Inferences about estimable functions of fixed effects
 - Point estimates
 - Confidence intervals
 - Tests of hypotheses
- (ii) Estimation of variance components (elements of G and R)
- (iii) Predictions of random effects (blup)
- (iv) Predictions of future observations

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Methods of Estimation

I. Ordinary Least Squares Estimation:

Normal equations (estimating equations):

$$(X^T X)b = X^T Y$$

and solutions have the form

$$b = (X^T X)^{-1} X^T Y$$

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The Gauss-Markov Theorem cannot be applied because it requires uncorrelated responses.

In these models

$$\begin{aligned} Var(Y) &= ZGZ^T + R \\ &\neq \sigma^2 I \end{aligned}$$

Hence, the OLS estimator of an estimable function $C^T \beta$ is not necessarily a best linear unbiased estimator (b.l.u.e.).

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- The OLS estimator for $C^T \beta$ is

$$C^T b = C^T (X^T X)^{-1} X^T Y$$

where

$$b = (X^T X)^{-1} X^T Y$$

is a solution to the normal equations.

- The OLS estimator $C^T b$ is a linear function of Y .
- $E(C^T b) = C^T \beta$

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- $Var(C^T b) =$

$$C^T(X^T X)^{-1} X^T(ZGZ^T + R)$$

$$X(X^T X)^{-1} C$$

- If $Y \sim N(X\beta, ZGZ^T + R)$, then $C^T b$ has a normal distribution with mean

$$C^T \beta$$

and covariance matrix

$$C^T(X^T X)^{-1} X^T(ZGZ^T + R)$$

$$X(X^T X)^{-1} C$$

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II. Generalized Least Squares

(GLS) Estimation:

Suppose

$$E(Y) = X\beta$$

and also suppose

$$\Sigma = Var(Y) = ZGZ^T + R$$

is known. Then a GLS estimator for β is any b that minimizes

$$Q(b) = (Y - Xb)^T \Sigma^{-1} (Y - Xb)$$

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The estimating equations are:

$$(X^T \Sigma^{-1} X)b = X^T \Sigma^{-1} Y$$

and

$$b_{GLS} = (X^T \Sigma^{-1} X)^{-1} (X^T \Sigma^{-1} Y)$$

is a solution.

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For any estimable function $C^T \beta$, the unique b.l.u.e. is

$$C^T b_{GLS} = C^T (X^T \Sigma^{-1} X)^{-1} X^T \Sigma^{-1} Y$$

with

$$Var(C^T b_{GLS}) = C^T (X^T \Sigma^{-1} X)^{-1} C$$

If $Y \sim N(X\beta, \Sigma)$, then

$$C^T b_{GLS} \sim N(C^T \beta, C^T (X^T \Sigma^{-1} X)^{-1} C)$$

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When G and/or R contain unknown parameters, you could obtain an “approximate BLUE” by replacing the unknown parameters with consistent estimators to obtain

$$\hat{\Sigma} = Z\hat{G}Z^T + \hat{R}$$

and

$$C^T b_{GLS}^* = C^T (X^T \hat{\Sigma}^{-1} X)^{-1} \hat{\Sigma}^{-1} Y$$

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- $C^T b_{GLS}^*$ is not a linear function of Y
- $C^T b_{GLS}^*$ is not a best linear unbiased estimator (BLUE)
- See Kackar and Harville (1981, 1984) for conditions under which $C^T b_{GLS}^*$ is an unbiased estimator for $C^T \beta$
- $C^T (X^T \hat{\Sigma}^{-1} X)^{-1} C$ tends to “underestimate” $\text{Var}(C^T b_{GLS}^*)$ (see Eaton (1984))
- For “large” samples

$$C^T b_{GLS}^* \sim N(C^T \beta, C^T (X^T \Sigma^{-1} X)^{-1} C)$$

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Variance component estimation

- Estimation of parameters in G and R
- Crucial to the estimation of estimable functions of fixed effects (e.g. $E(Y) = X\beta$)
- Of interest in its own right (sources of variation in the pigment paste production example)

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Basic Approaches

- (i) ANOVA methods (method of moments):
Set observed values of mean squares equal to their expectations and solve the resulting equations.
- (ii) Maximum likelihood estimation (ML)
- (iii) Restricted maximum likelihood estimation (REML)

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ANOVA method (Method of Moments)

- Compute an ANOVA table
- Equate mean squares to their expected values
- Solve the resulting equations

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Example 10.1 Penicillin production

$$Y_{ij} = \mu + \alpha_i + \beta_j + e_{ij}$$

where

$$B_j \sim NID(0, \sigma_\beta^2)$$

and

$$e_{ij} \sim NID(0, \sigma_e^2)$$

Source of Variation	d.f.	Sums of Squares
Blocks	4	$a \sum_{j=1}^b (\bar{Y}_{.j} - \bar{Y}_{..})^2 = SS_{blocks}$
Processes	3	$b \sum_{i=1}^a (\bar{Y}_{i.} - \bar{Y}_{..})^2 = SS_{processes}$
error	12	$\sum_{i=1}^a \sum_{j=1}^b (Y_{ij} - \bar{Y}_{i.} - \bar{Y}_{.j} + \bar{Y}_{..})^2 = SSE$
C. total	19	$\sum_{i=1}^a \sum_{j=1}^b (Y_{ij} - \bar{Y}_{..})^2$

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Start at the bottom:

$$MS_{error} = \frac{SSE}{(a-1)(b-1)}$$

$$E(MS_{error}) = \sigma_e^2$$

Then an unbiased estimator for σ_e is

$$\hat{\sigma}_e^2 = MS_{error}$$

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Next, consider the mean square for the random block effects:

$$MS_{blocks} = \frac{SS_{blocks}}{b-1}$$

$$E(MS_{blocks}) = \sigma_e^2 + a\sigma_\beta^2$$

\uparrow
 number of
 observations
 for each block

Then,

$$\sigma_\beta^2 = \frac{E(MS_{blocks}) - \sigma_e^2}{a}$$

$$= \frac{E(MS_{blocks}) - E(MS_{error})}{a}$$

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An unbiased estimator for σ_β^2 is

$$\hat{\sigma}_\beta^2 = \frac{MS_{blocks} - MS_{error}}{a}$$

For the penicillin data

$$\hat{\sigma}_e^2 = MS_{error} = 18.83$$

$$\begin{aligned}\hat{\sigma}_\beta^2 &= \frac{MS_{blocks} - MS_{error}}{4} \\ &= \frac{66.0 - 18.83}{4} = 11.79\end{aligned}$$

$$\begin{aligned}Var(Y_{ij}) &= \hat{\sigma}_\beta^2 + \hat{\sigma}_e^2 \\ &= 11.79 + 18.83 = 30.62\end{aligned}$$

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/* This is a program for analyzing the penicillin data from Box, Hunter, and Hunter. It is posted in the file

penclln.sas

First enter the data */

```
data set1;
infile 'penclln.dat';
input batch process $ yield;
run;

/* Compute the ANOVA table, formulas for
expectations of mean squares, process
means and their standard errors */

proc glm data=set1;
class batch process;
model yield = batch process / e e3;
random batch / q test;
lsmeans process / stderr pdiff tdiff;
output out=set2 r=resid p=yhat;
run;
```

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/* Compute a normal probability plot for
the residuals and the Shapiro-Wilk test
for normality */

```
proc rank data=set2 normal=blom out=set2;
var resid; ranks q;
run;

proc univariate data=set2 normal plot;
var resid;
run;

goptions cback=white colors=(black)
target=win device=winprt rotate=portrait;

axis1 label=(h=2.5 r=0 a=90 f=swiss 'Residuals')
value=(f=swiss h=2.0) w=3.0 length=5.0 in;

axis2 label=(h=2.5 f=swiss 'Standard
Normal Quantiles')
value=(f=swiss h=2.0) w=3.0 length=5.0 in;
```

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```
axis3 label=(h=2.5 f=swiss 'Production Process')
value=(f=swiss h=2.0) w=3.0 length=5.0 in;

symbol1 v=circle i=none h=2 w=3 c=black;

proc gplot data=set2;
plot resid*q / vaxis=axis1 haxis=axis2;
title h=3.5 f=swiss c=black
'Normal Probability Plot';
run;

proc gplot data=set2;
plot resid*process / vaxis=axis1 haxis=axis3;
title h=3.5 f=swiss c=black 'Residual Plot';
run;
```

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```
/* Fit the same model using PROC MIXED. Compute
   REML estimates of variance components. Note
   that PROC MIXED provides appropriate standard
   errors for process means. When block effects
   are random, PROC GLM does not provide correct
   standard errors for process means */
```

```
proc mixed data=set1;
  class process batch;
  model yield = process / ddfm=satterth solution;
  random batch / type=vc g solution cl alpha=.05;
  lsmeans process / pdiff tdiff;
run;
```

General Linear Models Procedure
Class Level Information

Class	Levels	Values
BATCH	5	1 2 3 4 5
PROCESS	4	A B C D

Number of observations in data set = 20

General Form of Estimable Functions

Effect	Coefficients
INTERCEPT	L1
BATCH 1	L2
2	L3
3	L4
4	L5
5	L1-L2-L3-L4-L5
PROCESS A	L7
B	L8
C	L9
D	L1-L7-L8-L9

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Type III Estimable Functions for: BATCH

Effect	Coefficients
INTERCEPT	0
BATCH 1	L2
2	L3
3	L4
4	L5
5	-L2-L3-L4-L5

Dependent Variable: YIELD

Source	DF	Sum of Squares	Mean Square	F Value	Pr > F
Model	7	334.00	47.71	2.53	0.0754
Error	12	226.00	18.83		
Cor. Total	19	560.00			

Type III Estimable Functions for: PROCESS

Effect	Coefficients
INTERCEPT	0
BATCH 1	0
2	0
3	0
4	0
5	0

PROCESS	A	L7
B	L8	
C	L9	
D	-L7-L8-L9	

R-Square	C.V.	Root MSE	YIELD Mean
0.596	5.046	4.3397	86.0

Source	DF	Type III SS	Mean Square	F Value	Pr > F
BATCH	4	264.0	66.0	3.50	0.0407
PROCESS	3	70.0	23.3	1.24	0.3387

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Tests of Hypotheses for Mixed Model
Analysis of Variance

Quadratic Forms of Fixed Effects in the
Expected Mean Squares
Source: Type III Mean Square for PROCESS

	PROCESS	PROCESS	PROCESS	PROCESS
	A	B	C	D
PROCESS A	3.750	-1.250	-1.250	-1.250
PROCESS B	-1.250	3.750	-1.250	-1.250
PROCESS C	-1.250	-1.250	3.750	-1.250
PROCESS D	-1.250	-1.250	-1.250	3.750

Dependent Variable: YIELD

Source: BATCH
Error: MS(Error)

Denominator			
DF	Type III MS	DF	MS
4	66	12	18.83

Source: PROCESS			
Error: MS(Error)			
Denominator			
DF	Type III MS	DF	MS
3	23.33	12	18.83

Least Squares Means

Source Type III Expected Mean Square
BATCH Var(Error) + 4 Var(BATCH)

PROCESS Var(Error) + Q(PROCESS)

Source	Type III Expected Mean Square	YIELD	Std LSMEAN	Pr > T	t-tests / p-values		
					t	p	
BATCH	Var(Error) + 4 Var(BATCH)	A 84	1.941	0.0001	1	.	-0.364 -1.822 -0.729
							0.722 0.093 0.480
PROCESS	Var(Error) + Q(PROCESS)	B 85	1.941	0.0001	2	0.364 .	-1.457 -0.364
							0.722 0.171 0.722
		C 89	1.941	0.0001	3	1.822 1.457 .	1.093
							0.094 0.171 0.296
		D 86	1.941	0.0001	4	0.729 0.364 -1.093 .	
							0.480 0.723 0.296

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The MIXED Procedure

Iteration History

Model Information

Iteration	Eval	-2 Res Log Like	Criterion
0	1	106.59285141	
1	1	103.82994387	0.00000000

Convergence criteria met.

Data Set WORK.SET1
Dependent Variable yield
Covariance Structure Variance Components
Estimation Method REML
Residual Variance Method Profile
Fixed Effects SE Method Model-Based
Degrees of Freedom Method Satterthwaite

Row	Effect	batch	Col1	Col2	Col3	Col4	Col5
1	batch	1	11.7917				
2	batch	2		11.7917			
3	batch	3			11.7917		
4	batch	4				11.7917	
5	batch	5					11.7917

Class Level Information

Class Levels Values

Covariance Parameter Estimates

PROCESS 4 A B C D
BATCH 5 1 2 3 4 5

batch 11.7917
Residual 18.8333

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Fit Statistics	
Res Log Likelihood	-51.9
Akaike's Information Criterion	-53.9
Schwarz's Bayesian Criterion	-53.5
-2 Res Log Likelihood	103.8

Solution for Random Effects						
Effect	batch	Std Err				
		Estimate	Pred	DF	t	Pr > t
batch	1	4.2879	2.2473	5.29	1.91	0.1115
batch	2	-2.1439	2.2473	5.29	-0.95	0.3816
batch	3	-0.7146	2.2473	5.29	-0.32	0.7627
batch	4	1.4293	2.2473	5.29	0.64	0.5513
batch	5	-2.8586	2.2473	5.29	-1.27	0.2564

Solution for Fixed Effects

Effect	process	Estimate	Standard		DF	t Value	Pr > t
			Error	DF			
Intercept		86.0000	2.4749	11.1	34.75	<.0001	
process A	A	-2.0000	2.7447	12	-0.73	0.4802	
process B	B	-1.0000	2.7447	12	-0.36	0.7219	
process C	C	3.0000	2.7447	12	1.09	0.2958	
process D	D	0	

Solution for Random Effects

Effect	batch	Solution for Random Effects		
		Alpha	Lower	Upper
batch 1	1	0.05	-1.3954	9.9712
batch 2	2	0.05	-7.8273	3.5394
batch 3	3	0.05	-6.3980	4.9687
batch 4	4	0.05	-4.2540	7.1126
batch 5	5	0.05	-8.5419	2.8247

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Type 3 Tests of Fixed Effects

Effect	Num DF	Den DF	F Value		Pr > F
			F	Value	
process	3	12	1.24		0.3387

Least Squares Means

Effect	process	Est.	Standard				
			Error	DF	t Value	Pr > t	
process A	A	84.0000	2.4749	11.1	33.94	<.0001	
process B	B	85.0000	2.4749	11.1	34.35	<.0001	
process C	C	89.0000	2.4749	11.1	35.96	<.0001	
process D	D	86.0000	2.4749	11.1	34.75	<.0001	

Differences of Least Squares Means

Effect	process	Estimate	Standard				
			Error	DF	t	Pr > t	
process A B	B	-1.0000	2.7447	12	-0.36	0.7219	
process A C	C	-5.0000	2.7447	12	-1.82	0.0935	
process A D	D	-2.0000	2.7447	12	-0.73	0.4802	
process B C	C	-4.0000	2.7447	12	-1.46	0.1707	
process B D	D	-1.0000	2.7447	12	-0.36	0.7219	
process C D	D	3.0000	2.7447	12	1.09	0.2958	

Inferences about treatment means:

$$Y_{ij} = \mu + \alpha_i + \beta_j + e_{ij}$$

Consider the sample mean (one observation for each treatment in each block):

$$\bar{Y}_{i\cdot} = \frac{1}{b} \sum_{j=1}^b Y_{ij}$$

$$E(\bar{Y}_{i\cdot}) = \begin{cases} \mu + \alpha_i & \text{for random block effects} \\ \beta_j \sim NID(0, \sigma_\beta^2) & \\ \mu + \alpha_i + \frac{1}{b} \sum_{j=1}^b \beta_j & \text{for fixed block effects} \end{cases}$$

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Confidence Intervals

Fixed additive block effects:

and

$$\begin{aligned}
 Var(\bar{Y}_{i\cdot}) &= Var\left(\frac{1}{b} \sum_{j=1}^b Y_{ij}\right) \\
 &= \frac{1}{b^2} \sum_{j=1}^b Var(Y_{ij}) \\
 &= \begin{cases} \frac{1}{b}(\sigma_e^2 + \sigma_b^2) & \text{random block effects} \\ \frac{1}{b}(\sigma_e^2) & \text{fixed block effects} \end{cases}
 \end{aligned}$$

The standard error for $\bar{Y}_{i\cdot}$ is

$$S_{\bar{Y}_{i\cdot}} = \sqrt{\frac{1}{b} MS_{error}} = 1.941$$

A $(1 - \alpha) \times 100\%$ confidence interval for

$$\mu + \alpha_i + \frac{1}{b} \sum_{j=1}^b \beta_j$$

is

$$\bar{Y}_{i\cdot} \pm t_{(a-1)(b-1), \frac{\alpha}{2}} \sqrt{\frac{1}{b} MS_{error}}$$

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t-tests:

Reject $H_0 : \mu + \alpha_i + \frac{1}{b} \sum_{j=1}^b \beta_j = d$ if

$$|t| = \frac{|\bar{Y}_{i\cdot} - d|}{\sqrt{\frac{1}{b} MS_{error}}} > t_{(a-1)(b-1), \frac{\alpha}{2}}$$

- This is what is done by the LSMEANS option in the GLM procedure in SAS, even when you specify RANDOM BATCH;

- This is what is done by the MIXED procedure in SAS when batch effects are not random

Models with random additive block effects:

$$\begin{aligned}
 S_{\bar{Y}_{i\cdot}}^2 &= \frac{1}{b} (\hat{\sigma}_e^2 + \hat{\sigma}_\beta^2) \\
 &= \frac{1}{b} \left(MS_{error} + \frac{MS_{blocks} - MS_{error}}{a} \right) \\
 &= \frac{a-1}{ab} MS_{error} + \frac{1}{ab} MS_{blocks} \\
 &= \frac{1}{ab(b-1)} [SS_{error} + SS_{blocks}] \\
 &\quad \nearrow \sigma_e^2 \chi_{(a-1)(b-1)}^2 \quad \nwarrow (\sigma_e^2 + a\sigma_\beta^2) \chi_{(b-1)}^2
 \end{aligned}$$

Hence, the distribution of $S_{\bar{Y}_{i\cdot}}^2$ is not a multiple of a central chi-square random variable.

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Standard error for \bar{Y}_i , is

$$\begin{aligned} S_{\bar{Y}_i} &= \sqrt{\frac{a-1}{ab} MS_{error} + \frac{1}{ab} MS_{blocks}} \\ &= 2.4749 \end{aligned}$$

An approximate $(1 - \alpha) \times 100\%$ confidence interval for $\mu + \alpha_i$ is

$$\bar{Y}_i \pm t_{\nu, \frac{\alpha}{2}} \sqrt{\frac{a-1}{ab} MS_{error} + \frac{1}{ab} MS_{blocks}}$$

where

$$\begin{aligned} v &= \frac{\left[\frac{a-1}{ab} MS_{error} + \frac{1}{ab} MS_{blocks} \right]^2}{\frac{\left(\frac{a-1}{ab} MS_{error} \right)^2}{(a-1)(b-1)} + \frac{\left(\frac{1}{ab} MS_{blocks} \right)^2}{b-1}} \\ &= \frac{\left[\frac{4-1}{(4)(5)} MS_{error} + \frac{1}{ab} MS_{blocks} \right]^2}{\frac{\left(\frac{a-1}{ab} MS_{error} \right)^2}{(a-1)(b-1)} + \frac{\left(\frac{1}{ab} MS_{blocks} \right)^2}{b-1}} = 11.075 \end{aligned}$$

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Result 10.1: Cochran-Satterthwaite approximation

Suppose MS_1, MS_2, \dots, MS_k are mean squares with

- independent distributions
- degrees of freedom = df_i
- $\frac{(df_i)MS_i}{E(MS_i)} \sim \chi^2_{df_i}$

Then, for positive constants

$$a_i > 0, \quad i = 1, 2, \dots, k$$

the distribution of

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$$S^2 = a_1 MS_1 + a_2 MS_2 + \dots + a_k MS_k$$

is approximated by

$$\frac{v S^2}{E(S^2)} \underset{\sim}{\sim} \chi^2_v$$

where

$$v = \frac{[E(S^2)]^2}{\frac{[a_1 E(MS_1)]^2}{df_1} + \dots + \frac{[a_k E(MS_k)]^2}{df_k}}$$

is the value for the degrees of freedom.

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In practice, the degrees of freedom are evaluated as

$$V = \frac{[S^2]^2}{\frac{(a_1 MS_1)^2}{df_1} + \dots + \frac{(a_k MS_k)^2}{df_k}}$$

These are called the Cochran-Satterthwaite degrees of freedom.

Cochran, W.G. (1951) Testing a Linear Relation among Variances, *Biometrics* 7, 17-32.

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Difference between two means:

$$E(\bar{Y}_{i\cdot} - \bar{Y}_{k\cdot})$$

$$= E\left(\frac{1}{b} \sum_{j=1}^b Y_{ij} - \frac{1}{b} \sum_{j=1}^b Y_{kj}\right)$$

$$= E\left(\frac{1}{b} \sum_{j=1}^b (Y_{ij} - Y_{kj})\right)$$

$$= E\left(\frac{1}{b} \sum_{j=1}^b (\mu + \alpha_i + \beta_j + \epsilon_{ij} - \mu - \alpha_k - \beta_j - \epsilon_{kj})\right)$$

$$= \alpha_i - \alpha_k + \frac{1}{b} \sum_{j=1}^b \frac{E(\epsilon_{ij} - \epsilon_{kj})}{b}$$

↑ this is zero

$$= \alpha_i - \alpha_k$$

$$= (\mu + \alpha_i) - (\mu + \alpha_k)$$

whether block effects are fixed or random.

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$$\begin{aligned} Var(\bar{Y}_{i\cdot} - \bar{Y}_{k\cdot}) &= Var\left(\alpha_i - \alpha_k + \frac{1}{b} \sum_{j=1}^b (\epsilon_{ij} - \epsilon_{kj})\right) \\ &= \frac{1}{b^2} \sum_{j=1}^b Var(\epsilon_{ij} - \epsilon_{kj}) \\ &= \frac{2\sigma_e^2}{b} \end{aligned}$$

The standard error for $\bar{Y}_{i\cdot} - \bar{Y}_{k\cdot}$ is

$$S_{\bar{Y}_{i\cdot} - \bar{Y}_{k\cdot}} = \sqrt{\frac{2MS_{error}}{b}}$$

A $(1 - \alpha) \times 100\%$ confidence interval for $\alpha_i - \alpha_k$ is

$$(\bar{Y}_{i\cdot} - \bar{Y}_{k\cdot}) \pm t_{(a-1)(b-1), \frac{\alpha}{2}} \sqrt{\frac{2MS_{error}}{b}}$$

↑
d.f. for MS_{error}

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t-test:

Reject $H_0 : \alpha_i - \alpha_k = 0$ if

$$|t| = \frac{|\bar{Y}_{i\cdot} - \bar{Y}_{k\cdot}|}{\sqrt{\frac{2MS_{error}}{b}}} > t_{(a-1)(b-1), \frac{\alpha}{2}}$$

↑
d.f. for MS_{error}

```
# Analyze the penicillin data from Box,
# Hunter, and Hunter. This code is
# posted as penclln.ssc
```

```
# Enter the data into a data frame and
# change the Batch and Process variables
# into factors
```

```
> penclln <- read.table("penclln.dat",
+   col.names=c("Batch", "Process", "Yield"))
> penclln$Batch <- as.factor(penclln$Batch)
> penclln$Process <- as.factor(penclln$Process)
> penclln
```

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Batch	Process	Yield
1	1	89
2	1	88
3	1	97
4	1	94
5	2	84
6	2	77
7	2	92
8	2	79
9	3	81
10	3	87
11	3	87
12	3	85
13	4	87
14	4	92
15	4	89
16	4	84
17	5	79
18	5	81
19	5	80
20	5	88

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```

# Construct a profile plot.  UNIX users
# should use the motif( ) command to open
# a graphics window

> attach(penclln)
> means <- tapply(Yield,list(Process,Batch),mean)

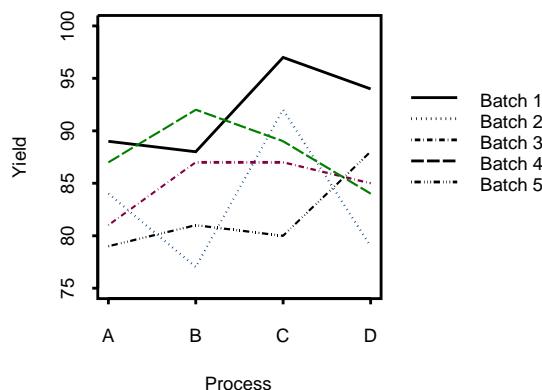
> par(fin=c(6,7),cex=1.2,lwd=3,mex=1.5)
> x.axis <- unique(Process)
> matplot(c(1,4), c(75,100), type="n", xaxt="n",
+   xlab="Process", ylab="Yield",
+   main= "Penicillin Production Results")
> axis(1, at=(1:4)*1, labels=c("A", "B", "C", "D"))
> matlines(x.axis,means,type='l',lty=1:5,lwd=3)

> legend(4.2,95, legend=c('Batch 1','Batch 2',
+ 'Batch 3','Batch 4','Batch 5'), lty=1:5,bty='n')
> detach()

```

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Penicillin Production Results



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```

# Use the lme( ) function to fit a model
# with additive batch (random) and process
# (fixed) effects and create diagnostic plots.

```

```

> options(contrasts=c("contr.treatment",
+ "contr.poly"))

> penclln.lme <- lme(Yield ~ Process,
+   random= ~ 1|Batch, data=penclln,
+   method=c("REML"))

> summary(penclln.lme)

```

```

Linear mixed-effects model fit by REML
Data: penclln
      AIC      BIC      logLik
83.28607 87.92161 -35.64304

```

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```
Random effects:
```

```
Formula: ~ 1 | Batch
```

```
    (Intercept) Residual
```

```
StdDev: 3.433899 4.339739
```

```
Fixed effects: Yield ~ Process
```

	Value	Std.Error	DF	t-value	p-value
(Intercept)	84	2.474874	12	33.94113	<.0001
Process2	1	2.744692	12	0.36434	0.7219
Process3	5	2.744692	12	1.82170	0.0935
Process4	2	2.744692	12	0.72868	0.4802

```
Correlation:
```

	(Intr)	Prcss2	Prcss3
Process2	-0.555		
Process3	-0.555	0.500	
Process4	-0.555	0.500	0.500

```
Standardized Within-Group Residuals:
```

Min	Q1	Med	Q3	Max
-1.415158	-0.5017351	-0.1643841	0.6829939	1.28365

```
Number of Observations: 20
```

```
Number of Groups: 5
```

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```
> # Estimated parameters for fixed effects  
> coef(penclln.lme)
```

	(Intercept)	Process2	Process3	Process4
1	88.28788	1	5	2
2	81.85606	1	5	2
3	83.28535	1	5	2
4	85.42929	1	5	2
5	81.14141	1	5	2

```
> # BLUP's for random effects  
> ranef(penclln.lme)
```

	(Intercept)
1	4.2878780
2	-2.1439390
3	-0.7146463
4	1.4292927
5	-2.8585854

```
> names(penclln.lme)
```

[1]	"modelStruct"	"dims"	"contrasts"
[4]	"coefficients"	"varFix"	"sigma"
[7]	"apVar"	"logLik"	"numIter"
[10]	"groups"	"call"	"method"
[13]	"fitted"	"residuals"	"fixDF"

```
> # Construct ANOVA table for fixed effects  
> anova(penclln.lme)
```

	numDF	denDF	F-value	p-value
(Intercept)	1	12	2241.213	<.0001
Process	3	12	1.239	0.3387

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```
> # Confidence intervals for fixed effects  
> # and estimated standard deviations  
> intervals(penclln.lme)
```

```
Approximate 95% confidence intervals
```

```
Fixed effects:
```

	lower	est.	upper
(Intercept)	78.6077137	84	89.39229
Process2	-4.9801701	1	6.98017
Process3	-0.9801701	5	10.98017
Process4	-3.9801701	2	7.98017

```
Random Effects:
```

```
Level: Batch
```

	lower	est.	upper
sd((Intercept))	0.8555882	3.433899	13.78193

```
Within-group standard error:
```

	lower	est.	upper
	2.464606	4.339739	7.64152

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```

> # Create a listing of the original data
> # residuals and predicted values

> data.frame(penclln$Process,penclln$Batch,
+             penclln$Yield,
+             Pred=penclln.lme$fitted,
+             Resid=round(penclln.lme$resid,3))

  X1 X2 X3 Pred.fixed Pred.Batch Resid.fixed Resid.Batch
1  1  1 89      84  88.28788       5    0.712
2  2  1 88      85  89.28788       3   -1.288
3  3  1 97      89  93.28788       8    3.712
4  4  1 94      86  90.28788       8    3.712
5  1  2 84      84  81.85606       0   2.144
6  2  2 77      85  82.85606      -8   -5.856
7  3  2 92      89  86.85606       3    5.144
8  4  2 79      86  83.85606      -7   -4.856
9  1  3 81      84  83.28535      -3   -2.285
10 2  3 87      85  84.28535       2    2.715
11 3  3 87      89  88.28535      -2   -1.285
12 4  3 85      86  85.28535      -1   -0.285
13 1  4 87      84  85.42929       3    1.571
14 2  4 92      85  86.42929       7    5.571
15 3  4 89      89  90.42929       0   -1.429
16 4  4 84      86  87.42929      -2   -3.429
17 1  5 79      84  81.14141      -5   -2.141
18 2  5 81      85  82.14141      -4   -1.141
19 3  5 80      89  86.14141      -9   -6.141
20 4  5 88      86  83.14141       2    4.859

```

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```
> # Create residual plots
```

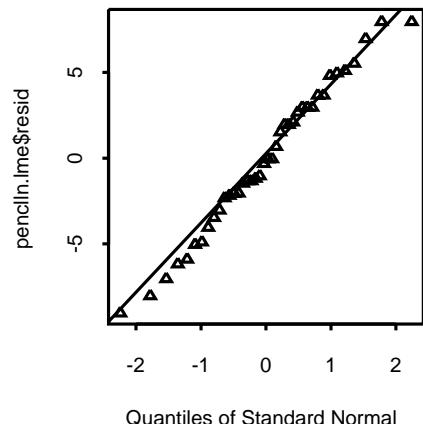
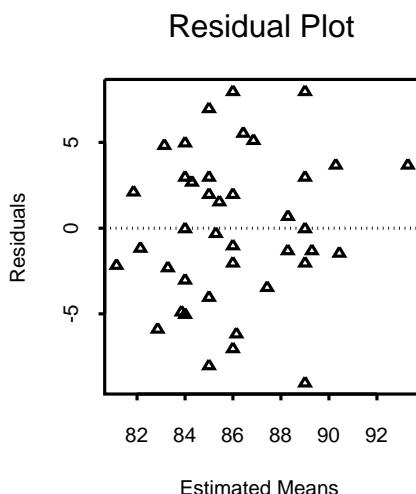
```

> frame( )
> par(fin=c(7,7),cex=1.2,lwd=3,mex=1.5)
> plot(penclln.lme$fitted, penclln.lme$resid,
+       xlab="Estimated Means",
+       ylab="Residuals",
+       main="Residual Plot")
> abline(h=0, lty=2, lwd=3)

> qqnorm(penclln.lme$resid)
> qqline(penclln.lme$resid)

```

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Example 10.2 Pigment production

In this example the main objective is the estimation of the variance components

<u>Source of Variation</u>	<u>d.f.</u>	<u>MS</u>	<u>E(MS)</u>
Batches	15-1=14	86.495	$\sigma_e^2 + 2\sigma_\delta^2 + 4\sigma_\beta^2$
Samples in Batches	15(2-1)=15	57.983	$\sigma_e^2 + 2\sigma_\delta^2$
Tests in Samples	(30)(2-1)=30	0.917	σ_e^2

Estimates of variance components:

$$\hat{\sigma}_e^2 = MS_{tests} = 0.917$$

$$\hat{\sigma}_\delta^2 = \frac{MS_{samples} - MS_{tests}}{2} = 28.533$$

$$\hat{\sigma}_\beta^2 = \frac{MS_{batches} - MS_{samples}}{4} = 7.128$$

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```
/* This is a SAS program for analyzing  
data from a nested or heirarchical  
experiment. This program is posted  
as
```

```
pigment.sas
```

```
The data are measurements of moisture  
content of a pigment taken from Box,  
Hunter and Hunter (page 574).*/
```

```
data set1;  
  infile 'pigment.dat';  
  input batch sample test y;  
  run;
```

```
proc print data=set1;  
  run;
```

```
/* The "random" statement in the following  
GLM procedure prints of formulas for  
expectations of mean squares. These results  
are used in variance component estimation */
```

```
proc glm data=set1;  
  class batch sample;  
  model y = batch sample(batch) / e1;  
  random batch sample(batch) / q test;  
  run;
```

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```

/* Alternatively, REML estimates of variance
components are produced by the MIXED
procedure in SAS. Note that there are
no terms on the right of the equal sign in
the model statement because the only
non-random effect is the intercept. */

proc mixed data=set1;
  class batch sample test;
  model y = ;
  random batch sample(batch);
  run;

/* Use the MIXED procedure in SAS to compute
maximum likelihood estimates of variance
components */

proc mixed data=set1 method=ml;
  class batch sample test;
  model y = ;
  random batch sample(batch);
  run;

```

OBS	BATCH	SAMPLE	TEST	Y
1	1	1	1	40
2	1	1	2	39
3	1	2	1	30
4	1	2	2	30
5	2	1	1	26
6	2	1	2	28
7	2	2	1	25
8	2	2	2	26
9	3	1	1	29
10	3	1	2	28
11	3	2	1	14
12	3	2	2	15
13	4	1	1	30
14	4	1	2	31
15	4	2	1	24
16	4	2	2	24
17	5	1	1	19
18	5	1	2	20
19	5	2	1	17
20	5	2	2	17
21	6	1	1	33
22	6	1	2	32
23	6	2	1	26
24	6	2	2	24
25	7	1	1	23
26	7	1	2	24
27	7	2	1	32
28	7	2	2	33
29	8	1	1	34
30	8	1	2	34

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OBS	BATCH	SAMPLE	TEST	Y
31	8	2	1	29
32	8	2	2	29
33	9	1	1	27
34	9	1	2	27
35	9	2	1	31
36	9	2	2	31
37	10	1	1	13
38	10	1	2	16
39	10	2	1	27
40	10	2	2	24
41	11	1	1	25
42	11	1	2	23
43	11	2	1	25
44	11	2	2	27
45	12	1	1	29
46	12	1	2	29
47	12	2	1	31
48	12	2	2	32
49	13	1	1	19
50	13	1	2	20
51	13	2	1	29
52	13	2	2	30
53	14	1	1	23
54	14	1	2	24
55	14	2	1	25
56	14	2	2	25
57	15	1	1	39
58	15	1	2	37
59	15	2	1	26
60	15	2	2	28

General Linear Models Procedure
Class Level Information

Class	Levels	Values
BATCH	15	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
SAMPLE	2	1 2

Number of observations in the data set = 60

Dependent Variable: Y

Source	DF	Sum of Squares	Mean Square	F Value	Pr > F
Model	29	2080.68	71.7477	78.27	0.0001
Error	30	27.5000	0.9167		
C.Total	59	2108.18333333			

Source	DF	Type I SS	Mean Square	F Value	Pr > F
BATCH	14	1210.93	86.4952	94.36	0.0001
SAMPLE(BATCH)	15	869.75	57.9833	63.25	0.0001

773

774

Source Type I Expected Mean Square

BATCH Var(Error) + 2 Var(SAMPLE(BATCH))
 + 4 Var(BATCH)

SAMPLE(BATCH) Var(Error) + 2 Var(SAMPLE(BATCH))

Dependent Variable: y

Source	DF	Type I SS	MS	F	Pr>F
batch	14	1210.933	86.495	1.49	0.2256
Error:	15	869.750	57.983		
MS(sample(batch))					

The MIXED Procedure

Class Level Information

	Class	Levels	Values
BATCH	15	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	
SAMPLE	2	1 2	
TEST	2	1 2	

REML Estimation Iteration History

Iteration	Evaluations	Objective	Criterion
0	1	274.08096606	
1	1	183.82758851	0.00000000

Convergence criteria met.

775

Covariance Parameter Estimates (REML)

Cov Parm	Ratio	Estimate	Std Error	Z	Pr > Z
BATCH	7.7760	7.1280	9.7373	0.73	0.4642
SAMPLE(BATCH)	31.1273	28.5333	10.5869	2.70	0.0070
Residual	1.0000	0.9167	0.2367	3.87	0.0001

The MIXED Procedure

Class Level Information

	Class	Levels	Values
BATCH	15	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	
SAMPLE	2	1 2	
TEST	2	1 2	

Model Fitting Information for Y

Description	Value
Observations	60.0000
Variance Estimate	0.9167
Standard Deviation Estimate	0.9574
REML Log Likelihood	-146.131
Akaike's Information Criterion	-149.131
Schwarz's Bayesian Criterion	-152.247
-2 REML Log Likelihood	292.2623

ML Estimation Iteration History

Iteration	Evaluations	Objective	Criterion
0	1	273.55423884	
1	1	184.15844023	0.00000000

Convergence criteria met.

Covariance Parameter Estimates (MLE)						
Cov Parm	Ratio	Estimate	Std Error	Z	Pr > Z	
BATCH	6.2033	5.68639	9.07341	0.63	0.5309	
SAMPLE(BATCH)	31.1273	28.53333	10.58692	2.70	0.0070	
Residual	1.0000	0.91667	0.23668	3.87	0.0001	

Model Fitting Information for Y

Description	Value
Observations	60.0000
Variance Estimate	0.9167
Standard Deviation Estimate	0.9574
Log Likelihood	-147.216
Akaike's Information Criterion	-150.216
Schwarz's Bayesian Criterion	-153.357
-2 Log Likelihood	294.4311

778

779

Estimation of $\mu = E(Y_{ijk})$:

$$\hat{\mu} = \bar{Y}... = \frac{1}{bsr} \sum_{i=1}^b \sum_{j=1}^s \sum_{k=1}^r Y_{ijk}$$

$$E(\bar{Y}...) = \mu$$

$$Var(\bar{Y}...) = \frac{1}{bsr} (\sigma_e^2 + r\sigma_\delta^2 + Sr\sigma_\beta^2)$$

Standard error:

$$\begin{aligned} S_{\bar{Y}...} &= \sqrt{\frac{1}{bsr} (\hat{\sigma}_e^2 + r\hat{\sigma}_\delta^2 + sr\hat{\sigma}_\beta^2)} \\ &= \sqrt{\frac{1}{bsr} (MS_{Batches})} \\ &= \sqrt{\frac{86.495}{60}} = 1.4416 \end{aligned}$$

A 95% confidence interval for μ

$$\bar{Y}... \pm t_{14,.025} S_{\bar{Y}...}$$

↗
df for $MS_{Batches}$

Here, $t_{14,.025} = 2.510$ and the confidence interval is

$$26.783 \pm (2.510)(1.4416)$$

$$\Rightarrow (23.16, 30.40)$$

```
> # This file is stored as pigment.spl
> pigment <- read.table("pigment.dat",
+ col.names=c("Batch", "Sample", "Test", "Y"))
> pigment$Batch <- as.factor(pigment$Batch)
> pigment$Sample <- as.factor(pigment$Sample)
> pigment
```

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Batch	Sample	Test	Y
1	1	1	1 40
2	1	1	2 39
3	1	2	1 30
4	1	2	2 30
5	2	1	1 26
6	2	1	2 28
7	2	2	1 25
8	2	2	2 26
9	3	1	1 29
10	3	1	2 28
11	3	2	1 14
12	3	2	2 15
.	.	.	.
.	.	.	.

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```

> # The function raov() may be used for
> # balanced designs with only random effects,
> # and gives a conventional analysis including
> # the estimation of variance components.
> # The function varcomp() is more general. It
> # may be used to estimate variance components
> # for balanced or unbalanced mixed models.

> # raov(): Random Effects Analysis of Variance
>
> pigment.raov <- raov(Y ~ Batch/Sample,
+                         data=pigment)

> # or you could use
> # pigment.raov <- raov(Y ~ Batch +
> #                         Batch:Sample, data=pigment)
> # pigment.raov <- raov(Y ~ Batch +
> #                         Sample %in% Batch, data=pigment)

```

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```
> summary(pigment.raov)
```

	Df	Sum of Sq	Mean Sq	Est. Var.
Batch	14	1210.933	86.49524	7.12798
Sample %in% Batch	15	869.750	57.98333	28.53333
Residuals	30	27.500	0.91667	0.91667

```
> names(pigment.raov)
```

[1]	"coefficients"	"residuals"	"fitted.values"
[4]	"effects"	"R"	"rank"
[7]	"assign"	"df.residual"	"contrasts"
[10]	"terms"	"call"	"model"
[13]	"replications"	"ems.coef"	

```
> pigment.raov$rep
```

Batch	Sample	%in% Batch
4		2

```
> pigment.raov$ems.coef
```

Sample		
Batch	%in% Batch	Residuals
Batch	4	0
Sample %in% Batch	2	2
Residuals	1	1

783

```

> # The same variance component estimates can be
> # found using varcomp(), but this allows mixed
> # models and we first must declare which factors
> # are random using the is.random() function.
> # All factors in the data frame are established
> # as random effects by the following
>
> is.random(pigment) <- T
> is.random(pigment)
Batch Sample
T      T
>
> # The possible estimation methods are
> # "minque0": minimum norm quadratic estimators
> #             (the default)
> # "reml"   : residual (or reduced or restricted)
> #             maximum likelihood.
> # "ml"    : maximum likelihood.

```

784

```
> varcomp(Y ~ Batch/Sample, data=pigment,
+           method="reml")$var
```

Batch	Sample	%in% Batch	Residuals
7.12866		28.53469	0.916641

```
> varcomp(Y ~ Batch/Sample, data=pigment,
+           method="ml")$var
```

Batch	Sample	%in% Batch	Residuals
5.68638		28.53333	0.9166668

785

Properties of ANOVA methods for variance component estimation:

(i) Broad applicability

- easy to compute in balanced cases
- ANOVA is widely known
- not required to completely specify distributions for random effects

(ii) Unbiased estimators

(iii) Sampling distribution is not exactly known, even under the usual normality assumptions (except for $\hat{\sigma}_e^2 = MS_{error}$)

786

(iv) May produce negative estimates of variances

(v) REML estimates have the same values

- in simple balanced cases
- when ANOVA estimates of variance components are inside the parameter space

(vi) For unbalanced studies, there may be no “natural” way to choose

$$\hat{\sigma}^2 = \sum_{i=1}^k a_i MS_i$$

787

Result 10.2: If

MS_1, MS_2, \dots, MS_k are distributed independently with

$$\frac{(df_i) MS_i}{E(MS_i)} \sim \chi_{df_i}^2$$

and constants $a_i > 0$, $i = 1, 2, \dots, k$ are selected so that

$$\hat{\sigma}^2 = \sum_{i=1}^k a_i MS_i$$

has expectation σ^2 , then

$$Var(\hat{\sigma}^2) = 2 \sum_{i=1}^k \frac{a_i^2 [E(MS_i)]^2}{df_i}$$

788

and an unbiased estimator of this variance is

$$Var(\hat{\sigma}^2) = \frac{2a_i^2 MS_i^2}{(df_i + 2)}$$

Proof: Since $\frac{(df_i) MS_i}{E(MS_i)} \sim \chi_{df_i}^2$ and $E(\chi_{df_i}^2) = df_i$ and $Var(\chi_{df_i}^2) = 2df_i$,

it follows that

$$\begin{aligned} Var(MS_i) &= Var\left(\frac{E(MS_i)\chi_{df_i}^2}{df_i}\right) \\ &= \frac{2[E(MS_i)]^2}{df_i} \end{aligned}$$

789

From the independence of the MS_i 's, we have

$$\begin{aligned} Var(\hat{\sigma}^2) &= \sum_{i=1}^k a_i^2 Var(MS_i) \\ &= 2 \sum_{i=1}^k \frac{a_i^2 [E(MS_i)]^2}{df_i} \end{aligned}$$

Furthermore,

$$\begin{aligned} E(MS_i^2) &= Var(MS_i) + [E(MS_i)]^2 \\ &= \frac{2[E(MS_i)]^2}{df_i} + [E(MS_i)]^2 \\ &= \left(\frac{df_i + 2}{df_i} \right) [E(MS_i)]^2 \end{aligned}$$

790

Consequently,

$$E \left[2 \sum_{i=1}^k \frac{a_i^2 MS_i^2}{(df_i + 2)} \right] = Var(\hat{\sigma}^2)$$

A "standard error" for

$$\hat{\sigma}^2 = \sum_{i=1}^k a_i MS_i$$

could be reported as

$$S_{\hat{\sigma}^2} = \sqrt{2 \sum_{i=1}^k \frac{a_i^2 MS_i^2}{(df_i + 2)}}$$

791

Using the Cochran-Satterthwaite approximation (Result 10.1), an approximate $(1 - \alpha) \times 100\%$ confidence interval for σ^2 could be constructed as:

$$\begin{aligned} 1 - \alpha &\doteq Pr \left\{ \chi_{\nu, 1-\alpha/2}^2 \leq \frac{v\hat{\sigma}^2}{\sigma^2} \leq \chi_{\nu, \alpha/2}^2 \right\} \\ &= Pr \left\{ \frac{v\hat{\sigma}^2}{\chi_{\nu, \alpha/2}^2} \leq \sigma^2 \leq \frac{v\hat{\sigma}^2}{\chi_{\nu, 1-\alpha/2}^2} \right\} \end{aligned}$$

where $\hat{\sigma}^2 = \sum_{i=1}^k a_i MS_i$ and

$$v = \frac{\left[\sum_{i=1}^k a_i MS_i \right]^2}{\sum_{i=1}^k \frac{[a_i MS_i]^2}{df_i}}$$

792

10.3 Likelihood-based methods:

Consider the mixed model

$$\mathbf{Y}_{n \times 1} = \mathbf{X}\boldsymbol{\beta}_{p \times 1} + \mathbf{Z}\mathbf{u}_{q \times 1} + \mathbf{e}_{n \times 1}$$

where

$$\begin{bmatrix} \mathbf{u} \\ \mathbf{e} \end{bmatrix} \sim N \left(\begin{bmatrix} \mathbf{0} \\ \mathbf{0} \end{bmatrix}, \begin{bmatrix} \mathbf{G} & \mathbf{0} \\ \mathbf{0} & \mathbf{R} \end{bmatrix} \right)$$

Then,

$$\mathbf{Y}_{n \times 1} \sim N(\mathbf{X}\boldsymbol{\beta}, \Sigma)$$

where $\Sigma = \mathbf{Z}\mathbf{G}\mathbf{Z}^T + \mathbf{R}$

- Maximum Likelihood Estimation
- Restricted Maximum Likelihood Estimation (REML)

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Maximum Likelihood Estimation

Multivariate normal likelihood:

$$L(\beta, \Sigma; Y) = (2\pi)^{-n/2} |\Sigma|^{-1/2} \\ \times \exp \left\{ -\frac{1}{2} (Y - X\beta)^T \Sigma^{-1} (Y - X\beta) \right\}$$

The log-likelihood function is

$$\ell(\beta, \Sigma; Y) = -\frac{n}{2} \log(2\pi) - \frac{1}{2} \log(|\Sigma|) \\ - \frac{1}{2} (Y - X\beta)^T \Sigma^{-1} (Y - X\beta)$$

Given the values of the observed responses, Y , find values β and Σ that maximize the log-likelihood function.

794

This is a difficult computational problem:

- no analytic solution (except in some balanced cases)
- use iterative numerical methods
 - Need starting values (initial guesses at the values of $\hat{\beta}$ and $\hat{\Sigma} = Z\hat{G}Z^T + \hat{R}$).
 - local or global maxima?
 - what if $\hat{\Sigma}$ becomes singular or is not positive definite?

795

- Constrained optimization
 - estimates of variances cannot be negative
 - estimated correlations between -1 and 1
 - $\hat{\Sigma}$, \hat{G} , and \hat{R} are positive definite (or non-negative definite)
- Large sample distributional properties of estimators
 - consistency
 - normality
 - efficiency*

*not guaranteed for ANOVA methods

796

- Estimates of variance components tend to be too small

Consider a sample Y_1, \dots, Y_n from a $N(\mu, \sigma^2)$ distribution. An unbiased estimator for σ^2 is

$$S^2 = \frac{1}{n-1} \sum_{j=1}^n (Y_j - \bar{Y})^2$$

The MLE for σ^2 is

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{j=1}^n (Y_j - \bar{Y})^2$$

with

$$E(\hat{\sigma}^2) = \left(\frac{n-1}{n} \right) \sigma^2 < \sigma^2$$

797

Note that S^2 and $\hat{\sigma}^2$ are based on
“error contrasts”

$$\begin{aligned} e_1 &= Y_1 - \bar{Y} = \left(\frac{n-1}{n}, -\frac{1}{n}, \dots, -\frac{1}{n}\right) Y \\ &\vdots \\ e_n &= Y_n - \bar{Y} = \left(-\frac{1}{n}, -\frac{1}{n}, \dots, -\frac{1}{n}, \frac{n-1}{n}\right) Y \end{aligned}$$

whose distribution does not depend
on

$$\mu = E(Y_j) .$$

When $Y \sim N(\mu 1, \sigma^2 I)$,

$$e = \begin{bmatrix} e_1 \\ \vdots \\ e_n \end{bmatrix} = (I - P_1)Y \sim N(0, \sigma^2(I - P_1))$$

798

The MLE $\hat{\sigma}^2 = \frac{1}{n} \sum_{j=1}^n e_j^2$ fails to
acknowledge that e is restricted
to an $(n-1)$ -dimensional
space, i.e., $\sum_{j=1}^n e_j = 0$.

The MLE fails to make the
appropriate adjustment in
“degrees of freedom” needed
to obtain an unbiased estimator
for σ^2 .

799

Example: Suppose $n = 4$ and

$$Y \sim N(\mu 1, \sigma^2 I).$$

Then

$$\begin{aligned} e &= \begin{bmatrix} Y_1 - \bar{Y} \\ Y_2 - \bar{Y} \\ Y_3 - \bar{Y} \\ Y_4 - \bar{Y} \end{bmatrix} = (I - P_1)Y \\ &\sim N(0, \underbrace{\sigma^2(I - P_1)}_{\text{This covariance matrix is singular.}}) \end{aligned}$$

Here, $m = \text{rank}(I - P_1) = n - 1 = 3$.

800

Define

$$r = M e = M(I - P_X)Y$$

where

$$M = \begin{bmatrix} 1 & 1 & -1 & -1 \\ 1 & -1 & 1 & -1 \\ 1 & -1 & -1 & 1 \end{bmatrix}$$

has row rank equal to

$$m = \text{rank}(I - P_X).$$

Then

$$\begin{aligned} r &= \begin{bmatrix} r_1 \\ r_2 \\ r_3 \end{bmatrix} = \begin{bmatrix} Y_1 + Y_2 - Y_3 - Y_4 \\ Y_1 - Y_2 + Y_3 - Y_4 \\ Y_1 - Y_2 - Y_3 + Y_4 \end{bmatrix} \\ &= M(I - P_1)Y \\ &\sim N(0, \underbrace{\sigma^2 M(I - P_1) M^T}_{\text{call this } \sigma^2 W}) \end{aligned}$$

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(Restricted) likelihood equation:

$$0 = \frac{\partial \ell(\sigma^2; \mathbf{r})}{\partial \sigma^2} = \frac{-m}{2\sigma^2} + \frac{1}{2(\sigma^2)^2} \mathbf{r}^T \mathbf{W}^{-1} \mathbf{r}$$

Restricted Likelihood function:

$$L(\sigma^2; \mathbf{r}) = \frac{1}{(2\pi)^{M/2} |\sigma^2 \mathbf{W}|^{1/2}} e^{-\frac{1}{2\sigma^2} \mathbf{r}^T \mathbf{W}^{-1} \mathbf{r}}$$

Restricted Log-likelihood:

$$\begin{aligned} \ell(\sigma^2; \mathbf{r}) &= \frac{-m}{2} \log(2\pi) - \frac{m}{2} \log(\sigma^2) \\ &\quad - \frac{1}{2} \log|\mathbf{W}| - \frac{1}{2\sigma^2} \mathbf{r}^T \mathbf{W}^{-1} \mathbf{r} \end{aligned}$$

(Note that $|\sigma^2 \mathbf{W}| = (\sigma^2)^m |\mathbf{W}|$)

802

Solution (REML estimator for σ^2):

$$\begin{aligned} \hat{\sigma}_{REML}^2 &= \frac{1}{m} \mathbf{r}^T \mathbf{W}^{-1} \mathbf{r} \\ &= \frac{1}{m} \mathbf{Y}^T (\mathbf{I} - \mathbf{P}_1)^T \mathbf{M}^T (\mathbf{M}(\mathbf{I} - \mathbf{P}_1)\mathbf{M}^T)^{-1} \mathbf{M}(\mathbf{I} - \mathbf{P}_1)\mathbf{Y} \end{aligned}$$

↗

This is a projection of \mathbf{Y} onto the column space of $\mathbf{M}(\mathbf{I} - \mathbf{P}_1)$ which is the column space of $\mathbf{I} - \mathbf{P}_1$

$$\begin{aligned} &= \frac{1}{m} \mathbf{Y}^T (\mathbf{I} - \mathbf{P}_1) \mathbf{Y} \\ &= \frac{1}{n-1} \sum_{j=1}^n (\mathbf{Y}_j - \bar{\mathbf{Y}})^2 = S^2 \end{aligned}$$

803

REML (Restricted Maximum Likelihood) estimation

- Estimate parameters in

$$\Sigma = \mathbf{Z}\mathbf{G}\mathbf{Z}^T + \mathbf{R}$$

by maximizing the part of the likelihood that does not depend on $E(\mathbf{Y}) = \mathbf{X}\beta$

804

- Maximize a likelihood function for “error contrasts”
 - linear combinations of observations that do not depend on $\mathbf{X}\beta$
 - Find a set of $n - \text{rank}(\mathbf{X})$ linearly independent “error contrasts”

805

Mixed (normal-theory) model:

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\mathbf{u} + \mathbf{e}$$

where $\begin{bmatrix} \mathbf{u} \\ \mathbf{e} \end{bmatrix} \sim N\left(\begin{bmatrix} \mathbf{0} \\ \mathbf{0} \end{bmatrix}, \begin{bmatrix} \mathbf{G} & \mathbf{0} \\ \mathbf{0} & \mathbf{R} \end{bmatrix}\right)$

Then

$$\begin{aligned} L\mathbf{Y} &= L(\mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\mathbf{u} + \mathbf{e}) \\ &= LX\boldsymbol{\beta} + LZ\mathbf{u} + Le \end{aligned}$$

is invariant to $X\boldsymbol{\beta}$ if and only if
 $LX = 0$. But $LX = 0$ if and only if

$$L = M(I - P_X)$$

806

for some M .

$$(Here P_X = X(X^T X)^{-1} X^T)$$

To avoid losing information we must have

$$\begin{aligned} \text{row rank}(M) &= n - \text{rank}(X) \\ &= n - p \end{aligned}$$

Then a set of $n - p$ error contrasts is

$$\begin{aligned} \mathbf{r} &= M(I - P_X)\mathbf{Y} \\ &\sim N_{n-p}(0, M(I - P_X)\Sigma^{-1}(I - P_X)M^T) \end{aligned}$$

↗
call this W ,
then $\text{rank}(W) = n - p$
and W^{-1} exists.

807

The "Restricted" likelihood is

$$L(\Sigma; \mathbf{r}) = \frac{1}{(2\pi)^{(n-p)/2} |W|^{1/2}} e^{-\frac{1}{2}\mathbf{r}^T W^{-1} \mathbf{r}}$$

The resulting log-likelihood is

$$\begin{aligned} \ell(\Sigma; \mathbf{r}) &= \frac{-(n-p)}{2} \log(2\pi) - \frac{1}{2} \log|W| \\ &\quad - \frac{1}{2} \mathbf{r}^T W^{-1} \mathbf{r} \end{aligned}$$

808

For any $M_{(n-p) \times n}$ with row rank equal to

$$n - p = n - \text{rank}(X)$$

the log-likelihood can be expressed in terms of

$$\mathbf{e} = (\mathbf{I} - \mathbf{X}(\mathbf{X}\Sigma^{-1}\mathbf{X}^T)^{-1}\mathbf{X}^T\Sigma^{-1})\mathbf{Y}$$

as

$$\begin{aligned} \ell(\Sigma; \mathbf{e}) &= \text{constant} - \frac{1}{2}\log(|\Sigma|) \\ &\quad - \frac{1}{2}\log(|\mathbf{X}_*^T\Sigma^{-1}\mathbf{X}_*|) - \frac{1}{2}\mathbf{e}^T\Sigma^{-1}\mathbf{e} \end{aligned}$$

where \mathbf{X}_* is any set of $p = \text{rank}(X)$ linearly independent columns of \mathbf{X} .

809

Denote the resulting REML estimators as

$$\hat{\mathbf{G}} \quad \hat{\mathbf{R}} \quad \text{and} \quad \hat{\Sigma} = \mathbf{Z}\hat{\mathbf{G}}\mathbf{Z}^T + \hat{\mathbf{R}}$$

810

Estimation of fixed effects

For any estimable function $C\beta$, the blue is the generalized least squares estimator

$$C\mathbf{b}_{GLS} = C(\mathbf{X}^T\Sigma^{-1}\mathbf{X})^{-1}\mathbf{X}^T\Sigma^{-1}\mathbf{Y}$$

Using the REML estimator for

$$\Sigma = \mathbf{Z}\mathbf{G}\mathbf{Z}^T + \mathbf{R}$$

an approximation is

$$C\hat{\beta} = C(\mathbf{X}^T\hat{\Sigma}^{-1}\mathbf{X})^{-1}\mathbf{X}^T\hat{\Sigma}^{-1}\mathbf{Y}$$

and for “large” samples:

$$C\hat{\beta} \sim N(C\beta, C(\mathbf{X}^T\Sigma^{-1}\mathbf{X})^{-1}C^T)$$

811

Prediction of random effects:

Given the observed responses \mathbf{Y} , predict the value of \mathbf{u} .

For our model,

$$\begin{bmatrix} \mathbf{u} \\ \mathbf{e} \end{bmatrix} \sim N \left(\begin{bmatrix} \mathbf{0} \\ \mathbf{0} \end{bmatrix}, \begin{bmatrix} \mathbf{G} & \mathbf{0} \\ \mathbf{0} & \mathbf{R} \end{bmatrix} \right).$$

Then (from result 4.1)

$$\begin{aligned} \begin{bmatrix} \mathbf{u} \\ \mathbf{Y} \end{bmatrix} &= \begin{bmatrix} \mathbf{u} \\ \mathbf{X}\beta + \mathbf{Z}\mathbf{u} + \mathbf{e} \end{bmatrix} \\ &= \begin{bmatrix} \mathbf{0} \\ \mathbf{X}\beta \end{bmatrix} + \begin{bmatrix} \mathbf{I} & \mathbf{0} \\ \mathbf{Z} & \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{u} \\ \mathbf{e} \end{bmatrix} \\ &\sim N \left(\begin{bmatrix} \mathbf{0} \\ \mathbf{X}\beta \end{bmatrix}, \begin{bmatrix} \mathbf{G} & \mathbf{G}\mathbf{Z}^T \\ \mathbf{Z}\mathbf{G} & \mathbf{Z}\mathbf{G}\mathbf{Z}^T + \mathbf{R} \end{bmatrix} \right) \end{aligned}$$

812

The Best Linear Unbiased Predictor (BLUP): is the b.l.u.e. for

$$\begin{aligned}
 E(u|Y) &= E(u) + (GZ^T)(ZGZ^T + R)^{-1}(Y - E(Y)) \\
 &= 0 + GZ^T(ZGZ^T + R)^{-1}(Y - X\beta) \\
 &\quad \uparrow \\
 &\text{substitute the b.l.u.e. for } X\beta \\
 Xb_{GLS} &= X(X^T\Sigma^{-1}X)^{-1}X^T\Sigma^{-1}Y
 \end{aligned}$$

Then, the BLUP for u is

$$\begin{aligned}
 BLUP(u) &= GZ^T\Sigma^{-1}(Y - Xb_{GLS}) \\
 &= GZ^T\Sigma^{-1}(I - X(X^T\Sigma^{-1}X)^{-1}X^T\Sigma^{-1})Y
 \end{aligned}$$

when G and $\Sigma = ZGZ^T + R$ are known.

813

Substituting REML estimators \hat{G} and \hat{R} for G and R , an approximate BLUP for u is

$$\begin{aligned}
 \hat{u} &= \hat{G}Z^T\hat{\Sigma}^{-1}(I - X(X^T\hat{\Sigma}^{-1}X)^{-1}X^T\hat{\Sigma}^{-1})Y \\
 &= \hat{G}Z^T\hat{\Sigma}^{-1}(Y - \underline{X}\hat{\beta})
 \end{aligned}$$

For "large" samples, the distribution of \hat{u} is approximately multivariate normal with mean vector 0 and covariance matrix

$$GZ^T\Sigma^{-1}(I - P)\Sigma(I - P)\Sigma^{-1}ZG$$

where

$$P = X(X^T\Sigma^{-1}X)^{-1}X^T\Sigma^{-1}$$

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Given estimates \hat{G} , \hat{R} and
 $\hat{\Sigma} = Z\hat{G}Z^T + \hat{R}$,
 $\hat{\beta}$ and \hat{u} provide a solution to the mixed model equations:

$$\begin{bmatrix} X^T\hat{R}^{-1}X & X^T\hat{R}^{-1}Z \\ Z^T\hat{R}^{-1} & Z^T\hat{R}^{-1}Z + \hat{G}^{-1} \end{bmatrix} \begin{bmatrix} \hat{\beta} \\ \hat{u} \end{bmatrix} = \begin{bmatrix} X^T\hat{R}^{-1}Y \\ Z^T\hat{R}^{-1}Y \end{bmatrix}$$

A generalized inverse of

$$\begin{bmatrix} X^T\hat{R}^{-1}X & X^T\hat{R}^{-1}Z \\ Z^T\hat{R}^{-1} & Z^T\hat{R}^{-1}Z + \hat{G}^{-1} \end{bmatrix}$$

is used to approximate the covariance matrix for $\begin{bmatrix} \hat{\beta} \\ \hat{u} \end{bmatrix}$

815

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