

Range and Kernel of a general linear Transformation -

Problem Given a linear transformation $T: V \rightarrow W$ where V and W are vector spaces of dimensions n and m , respectively. How do we find $\text{Ker } T$ and $\text{Range } T$?

Theorem Fix a basis B for V and a basis C for W .

$$B = \{ \vec{u}_1, \dots, \vec{u}_n \}$$

$$C = \{ \vec{v}_1, \dots, \vec{v}_m \}$$

Consider the matrix

$$A_{BC} = [[\vec{u}_1]_C \quad [\vec{u}_2]_C \quad \dots \quad [\vec{u}_n]_C]$$

Then for every $\vec{x} \in V$,

$$[T\vec{x}]_C = ABC[\vec{x}]_B$$

This theorem reduces the analysis of every linear transformation on any space to the analysis of a matrix transformation ABC from \mathbb{R}^n to \mathbb{R}^m .

It says that the following commutative diagram holds.

$$\begin{array}{ccc} V & \xrightarrow{T} & W \\ \downarrow []_B & & \downarrow []_C \\ \mathbb{R}^n & \xrightarrow{ABC} & \mathbb{R}^m \end{array}$$

EXAMPLE 1

consider $T: P_2 \rightarrow \mathbb{R}^2$

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$$T(p) = \begin{bmatrix} p(0) \\ p(1) \end{bmatrix}$$

Fix basis in P_2 , $B = \{1, t, t^2\}$.

Fix basis in \mathbb{R}^2 , $C = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$.

The matrix

$$A_{BC} = \left[\begin{array}{ccc} [T(1)]_C & [T(t)]_C & [T(t^2)]_C \end{array} \right] =$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

For a general $p(t) = a + bt + ct^2$

$$T(p) = \begin{bmatrix} a \\ a \end{bmatrix} \quad [T(p)]_C = \begin{bmatrix} a \\ a \end{bmatrix}$$

$$[\mathbf{w}]_B = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

EXAMPLE 2

Consider $T: \mathcal{M}_{2,2} \rightarrow \mathcal{M}_{2,2}$.

defined as

$$T(A) = zA - A^T$$

this is a linear

transformation

$$B = \left\{ \overset{A_1}{\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}}, \overset{A_2}{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}}, \overset{A_3}{\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}}, \overset{A_4}{\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}} \right\}$$

$$C = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\}$$

calculate

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$$T(A_1) = z \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

$$T(A_2) = \begin{pmatrix} 0 & z \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & z \\ -1 & 0 \end{pmatrix}$$

$$T(A_3) = \begin{pmatrix} 0 & 0 \\ z & 0 \end{pmatrix} - \begin{pmatrix} 0 & +1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ z & 0 \end{pmatrix}$$

$$T(A_3) = \begin{pmatrix} 0 & 0 \\ 0 & z \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\{T(A_1)\}_C = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\{T(A_3)\}_C = \begin{pmatrix} 0 \\ -1 \\ z \\ 0 \end{pmatrix}$$

$$\{T(A_2)\}_C = \begin{pmatrix} 0 \\ z \\ -1 \\ 0 \end{pmatrix}$$

$$\{T(A_4)\}_C = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

$$A_{BC} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & z & -1 & 0 \\ 0 & -1 & z & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

The matrix A_B is used to determine
the kernel and the range of T

To do this we need to introduce the
Inverse coordinatization, i.e., inverse
coordinate map. Recall coordinate
map $[]_B$

$$V \xrightarrow{[]_B} \mathbb{R}^n$$

The inverse coordinate map $[]_B^{-1}$

$$\mathbb{R}^n \xrightarrow{[]_B^{-1}} V$$

it works like.

$$(B = \vec{u}_1, \dots, \vec{u}_n)$$

$$\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \longrightarrow x_1 \vec{u}_1 + x_2 \vec{u}_2 + \dots + x_n \vec{u}_n$$

EXAMPLE

$$\text{Let } B = \{1, 1+t, t^2\}$$

consider $\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ - We have $\left[\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \right]_B^{-1} =$

$$1 + 2(1+t) + 3t^2 \quad \checkmark$$

ALGORITHM TO find kernel of T

- (1) Find $A_{B,C}$
- (2) Find $\text{Nul } A_{B,C}$ with B —
- (3) Do inverse coordinatization
this gives $\text{ker } T$.

EXAMPLE

Recall the linear transformation

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$T(\mu) = \begin{bmatrix} \mu @ 1 \\ \mu @ 1 \end{bmatrix}.$$

we have found

$$A_{BC} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

$$\text{Nul } A_{BC} = \left\{ \begin{pmatrix} 0 \\ x_2 \\ x_3 \end{pmatrix}, \quad x_2, x_3 \in \mathbb{R} \right\}$$

all these vectors are such that

$$A_{BC} \vec{x} = \mathbf{0}$$

Recall $B = \{1, t, t^2\}$ - Inverse
coordination gives

$$\text{ker } T = \{ x_2 t + x_3 t^2 \mid x_2, x_3 \in \mathbb{R} \}.$$

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EXAMPLE 2.

Recall the map $T(A) = zA - A^T$

we had
$$A_{BC} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & -1 & 0 \\ 0 & -1 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

The $\text{Nul } A_{BC} = \{ \vec{0} \}$ because the matrix A_{BC} is non singular

therefore $\text{ker}(T) = \left\{ \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right\}$ only the zero matrix gives "0".

ALGORITHM TO FIND Range of T

- (1) Find A_{bc}
- (2) Find $\text{Col}(A_{bc})$
- (3) Do inverse coordinatization (with c)

This gives range of T

EXAMPLE

Consider again

$$T(\mu) = \begin{Bmatrix} \mu e_1 \\ \mu e_1 \end{Bmatrix}$$

$$A_{bc} = \begin{Bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \end{Bmatrix}$$

$$\text{col } A_{bc} = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$$

~~$$\text{range of } T = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$$~~

$$\text{range } T = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$$

EXAMPLE
Consider again

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$$T(A) = zA - A^T$$

Inverses
Control realization

Col $A_{BC} = \mathbb{R}^4 \longrightarrow$ Range of $T = \mathcal{A}z, z$.

EXAMPLE

consider the linear transformation.

$$T(p) = \frac{d}{dt} p(t) + z p(t)$$

$$T: P_z \rightarrow P_z$$

$$\text{let } B = C = \{1, t, t^2\}$$

$$A_{BC} = ?$$

$$T(1) = z$$

$$T(t) = 1 + zt$$

$$T(t^2) = zt + zt^2$$

$$ABC = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 2 \\ 0 & 0 & 2 \end{bmatrix}$$

$$\text{ker } T = \{0\}.$$

$$\text{Range } T = P_2$$