

HWK #4 SOLUTIONS.

Section 2.2 #20

$$(A - AX)^{-1} = X^{-1}B \quad (3)$$

and $A - AX, A, X$ invertible

$$a) \quad B = X(A - AX)^{-1}$$

$$B(A - AX)X^{-1} = X(A - AX)^{-1}(A - AX)X^{-1}$$

$$= I$$

so B has an inverse given by

$$(A - AX)X^{-1}, \quad B \text{ is invertible.}$$

b) Multiply (3) on the left by X we get

$$X(A - AX)^{-1} = B$$

multiply on the right by $(A - AX)$;
we get.

$$X = B(A - AX) = BA - BAX$$

$$(I + BA)X = BA$$

$$X = (I + BA)^{-1}BA$$

$I + BA$ is invertible because.

$(I + BA) = BA X^{-1}$ is invertible since

$$(BA X^{-1})(X A^{-1} B^{-1}) = I$$

Section 2.2 # 32

$$\left[\begin{array}{ccc|ccc} 1 & -2 & 1 & 1 & 0 & 0 \\ 4 & -7 & 3 & 2 & 1 & 0 \\ -2 & 6 & -4 & 0 & 0 & 1 \end{array} \right] \sim$$

$$\left[\begin{array}{ccc|ccc} 1 & -2 & 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & -4 & 1 & 0 \\ 0 & 2 & -2 & 2 & 0 & 1 \end{array} \right] \sim$$

$$\left[\begin{array}{ccc|ccc} 1 & -2 & 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & -4 & 1 & 0 \\ 0 & 0 & 0 & \times & \times & \times \end{array} \right]$$

The inverse does not exist since there is a row of all zeros.

Section 2.3 #14

A lower triangular matrix is invertible if and only if all the elements on the main diagonal are different from zero.

Proof if $a_{11}, \dots, a_{nn} \neq 0$ (all)
then we can solve.

$$\begin{bmatrix} a_{11} & & & \\ & \ddots & & \\ & & \ddots & \\ & & & a_{nn} \end{bmatrix} \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix} \quad \vec{b}$$

independently of the value of \vec{b}

Just let $x_1 = \frac{b_1}{a_{11}}$

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replace into second eqn; it gives

$$a_{12} \frac{b_1}{a_{11}} + a_{22} x_2 = b_2$$

$$\Rightarrow x_2 = \frac{b_2}{a_{22}} - \frac{a_{12}}{a_{22}} \frac{b_1}{a_{11}}$$

and so on. Therefore the solution exist (and is unique) independently of the value of \vec{b} .

Moreover if one of the a_{ij} 's is zero there are values of \vec{b} for which the eqns have no solution.

Consider $\vec{x}_1, \dots, \vec{x}_{j-1}$ from previous steps

as above. At the J -th step we obtain:

$$a_{J1} \bar{x}_1 + a_{J2} \bar{x}_2 + \dots + a_{JJ-1} \bar{x}_{J-1} + 0 \bar{x}_J = b$$

so if $b \neq a_{J1} \bar{x}_1 + a_{J2} \bar{x}_2 + \dots + a_{JJ-1} \bar{x}_{J-1}$

the equation has no solution.

Therefore the system $A\vec{x} = \vec{b}$ does not have a solution for every \vec{b} and A is not invertible.

□

Section 2.4 # 8

$$\begin{bmatrix} A & B \\ 0 & I \end{bmatrix} \begin{bmatrix} x & y & z \end{bmatrix} = \begin{bmatrix} I & 0 & 0 \\ 0 & 0 & I \end{bmatrix}$$

$$\begin{cases} Ax = I & \Rightarrow x = A^{-1} \\ Ay = 0 & y = 0 \\ Az + B = 0 & z = -A^{-1}B \end{cases}$$

Assumption A is invertible square.

Section 2.4 # 10

$$\begin{bmatrix} I & 0 & 0 \\ C & I & 0 \\ A & B & I \end{bmatrix} \begin{bmatrix} I & 0 & 0 \\ z & I & 0 \\ x & y & I \end{bmatrix} =$$

$$\begin{bmatrix} I & 0 & 0 \\ 0 & I & 0 \\ 0 & 0 & I \end{bmatrix}$$

$$C + z = 0$$

$$z = -C$$

$$A + Bz + X = 0 \Rightarrow A + B(-C) = -X$$

$$\Rightarrow X = -A + BC$$

$$B + Y = 0$$

$$Y = -B$$

So the inverse is,

$$\begin{bmatrix} I & 0 & 0 \\ -C & I & 0 \\ -A + BC & -B & I \end{bmatrix}$$