

## Simplification to BE theory

Without simplification: (Climb or hover)

$$V_R^2 = [(V_0 + v_i)^2 + r(\Omega - \omega)^2] = (\Omega r)^2 \left[ \left( \frac{V_0 + v_i}{\Omega r} \right)^2 + (1 - a_1)^2 \right]$$

Assume no swirl  $\rightarrow a_1 = 0$ .

Assume  $|\Omega r| \gg |V_0 + v_i|$ .

$$\frac{V_0 + v_i}{\Omega r} \sim 0$$

$$V_R = \Omega r$$

Recall

$$dT = BC \frac{1}{2} \rho V_R^2 (C_l \cos \phi - C_d \sin \phi) dr$$

Using small angle approximation ( $\sin \phi \simeq \phi$ ,  $\cos \phi \simeq 1$ )

$$dT \simeq dL \simeq BC \frac{1}{2} \rho V_R^2 C_l dr$$

$C_d \phi \ll C_l$  as  $C_d$  and  $\phi$  are small quantities.

Recall

$$dQ = BC \left( \frac{1}{2} \rho V_R^2 \right) (C_l \sin \phi + C_d \cos \phi) r dr$$

$$dQ = BC \left( \frac{1}{2} \rho V_R^2 \right) (C_l \phi + C_d) r dr$$

Where  $C = C(r)$ ,  $C_l = C_l(r, \alpha, Re, M, \dot{\alpha})$ , and  $C_d = C_d(r, \alpha, Re, M, \dot{\alpha})$ .

$$\frac{dT}{\rho(\Omega r)^2 \pi R^2} = dC_T = \frac{BC}{\rho(\Omega r)^2 \pi R^2} \frac{1}{2} \rho V_R^2 C_l dr = \frac{BC}{\pi R} \frac{1}{2} \left( \frac{r}{R} \right)^2 C_l d\left( \frac{r}{R} \right)$$

$$dC_T = \frac{1}{2} \sigma_s(\bar{r})^2 C_l d(\bar{r})$$

$$C_T = \frac{1}{2} \int_0^1 \sigma_s(\bar{r})^2 C_l d(\bar{r})$$

Where  $\bar{r} = r/R$ ,  $\sigma_s = \frac{BC}{\pi R}$ , and  $C = C(\bar{r})$ .

$$\frac{dQ}{\rho(\Omega r)^2 \pi R^2 R} = dC_Q = \frac{BC}{\rho(\Omega r)^2 \pi R^2 R} \frac{1}{2} \rho V_R^2 (C_l \phi + C_d) r dr = \frac{BC}{\pi R} \frac{1}{2} \left( \frac{r}{R} \right)^2 (C_l \phi + C_d) \frac{r}{R} d\left( \frac{r}{R} \right)$$

$$dC_Q = \frac{1}{2} \sigma_s(\bar{r})^3 (C_l \phi + C_d) d(\bar{r})$$

$$C_Q = \frac{1}{2} \int_0^1 \sigma_s(\bar{r})^3 (C_l \phi + C_d) d(\bar{r})$$

Where

$$\phi = \tan^{-1} \left[ \frac{V_0 + v_i}{r(\Omega - \omega)} \right] \simeq \left[ \frac{V_0 + v_i}{r(\Omega - \omega)} \right] = \frac{U_P}{U_T}$$

$\lambda =$  Axial inflow ration  $= \frac{U_P}{\Omega R}$

$U_P$  is velocity normal to the tip path plane. When the rotor is in forward flight with no coning and no flapping

$$\lambda = \frac{V_0 \sin \alpha + v_i}{\Omega R}$$

In axial translation ( $\alpha = 90^\circ$ )

$$\lambda = \frac{V_0 + v_i}{\Omega R}$$

$$\phi \simeq \frac{U_P}{U_T} \simeq \frac{V_0 + v_i}{\Omega r} = \left( \frac{V_0 + v_i}{\Omega R} \right) \left( \frac{r}{R} \right) = \frac{\lambda}{\bar{r}}$$

Approximation ( $C_l = C_{l\alpha}(\alpha - \alpha_{L0})$ )

Where  $\alpha_{L0}$  is an angle of attack at zero lift.

$$\begin{aligned} C_l &\simeq C_{l\alpha}\alpha \simeq C_{l\alpha}(\theta - \phi) \\ C_T &= \frac{1}{2} \int_0^1 \sigma_s C_{l\alpha}(\theta - \phi)(\bar{r})^2 d(\bar{r}) \\ &= \frac{1}{2} \int_0^1 \sigma_s C_{l\alpha} \left( \theta - \frac{\lambda}{\bar{r}} \right) (\bar{r})^2 d(\bar{r}) \\ &= \frac{1}{2} \int_0^1 \sigma_s C_{l\alpha} (\theta \bar{r}^2 - \lambda \bar{r}) d(\bar{r}) \end{aligned}$$

Possible approximation for  $\theta$

- Uniform pitch:  $\theta = \theta_0 = \text{const.}$
- Linear twist:  $\theta = \theta_0 + \theta_{tw}\bar{r}$  or  $\theta = \theta_{0.75} + \theta_{tw}(\bar{r} - 3/4)$
- Ideal twist:  $\theta = \theta_{tw}\bar{r}$

Other approximations

- Constant chord ( $C$  is a constant)
- Uniform inflow ( $\lambda$  is a constant)

$$\begin{aligned} dC_T &= \frac{1}{2} \sigma_s(\bar{r})^2 C_l d(\bar{r}) \\ dC_Q &= \frac{1}{2} \sigma_s(\bar{r})^3 (C_l \phi + C_d) d(\bar{r}) \\ &= \frac{1}{2} \sigma_s(\bar{r})^3 (C_l \phi) d(\bar{r}) + \frac{1}{2} \sigma_s(\bar{r})^3 (C_d) d(\bar{r}) \\ &= dC_T \phi \bar{r} + \frac{1}{2} \sigma_s(\bar{r})^3 (C_d) d(\bar{r}) \\ &= dC_T \lambda + \frac{1}{2} \sigma_s(\bar{r})^3 (C_d) d(\bar{r}) \\ C_Q &= \int_0^1 \left[ dC_T \lambda + \frac{1}{2} \sigma_s(\bar{r})^3 (C_d) d(\bar{r}) \right] \end{aligned}$$

If  $\lambda$  is a constant (uniform inflow) and ( $C_d = C_{do}$ )

$$C_Q = C_T \lambda + \frac{\sigma}{8} C_{do}$$

Figure of Merit

$$\begin{aligned}
 FM &= \frac{\text{Induced power}}{\text{Actual power}} = \frac{\int (dT)v_i}{\int (dQ)\Omega} = \frac{\int (dT)v_i \rho(\Omega R)^3 (\pi R^2)}{\int (dQ)\Omega \rho(\Omega R)^3 (\pi R^2)} \\
 &= \frac{\int dC_T \left(\frac{v_i}{\Omega R}\right)}{\int dC_Q} = \frac{\int dC_T \lambda}{\int dC_Q}
 \end{aligned}$$

Neglecting swirl  $dC_Q = dC_T \lambda + \frac{1}{2} \sigma_s (\bar{r})^3 (C_d) d(\bar{r})$

$$FM = \frac{\int dC_T \lambda}{\int dC_T \lambda + \frac{1}{2} \sigma_s (\bar{r})^3 (C_d) d(\bar{r})}$$

If we assume uniform inflow  $\lambda = \text{const.}$

$$FM = \frac{C_T \lambda}{C_T \lambda + \frac{1}{2} \int \sigma_s (\bar{r})^3 (C_d) d(\bar{r})}$$

Constant chord ( $\sigma_s = \sigma$ )

$$FM = \frac{C_T \lambda}{C_T \lambda + \frac{1}{2} \sigma \int (\bar{r})^3 (C_d) d(\bar{r})}$$

If  $C_d = C_{do} = \text{const.}$

$$FM = \frac{C_T \lambda}{C_T \lambda + \frac{1}{2} \sigma C_{do} \int (\bar{r})^3 d(\bar{r})}$$

Integrating from  $\bar{r} = 0$  to 1 we get

$$FM = \frac{C_T \lambda}{C_T \lambda + \frac{\sigma C_{do}}{8}}$$

In hover for uniform inflow momentum theory gives  $\lambda = \sqrt{\frac{C_T}{2}}$

$$FM = \frac{C_T^{3/2} / \sqrt{2}}{C_T^{3/2} / \sqrt{2} + \frac{\sigma C_{do}}{8}}$$

To account for other losses a factor  $k$  is added to give

$$FM = \frac{C_T^{3/2} / \sqrt{2}}{k C_T^{3/2} / \sqrt{2} + \frac{\sigma C_{do}}{8}}$$

Where  $k$  is 1.0 to 1.15

The integration limits do not always go from  $\bar{r} = 0$  to 1.0. Parameters such as root cut-out and tip loss factor can change the limits.