

Curvature, Velocity, and Acceleration Formulas:

Unit Tangent Vector:

$$\vec{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|} = \frac{\vec{v}(t)}{\|\vec{v}(t)\|}.$$

Curvature:

1.) If a 2-D curve is given by $y = g(x)$, then

$$K(x) = \frac{|y''|}{[1 + (y')^2]^{3/2}} = \frac{|g''(x)|}{[1 + (g'(x))^2]^{3/2}}.$$

2.) If a curve is defined by parametric equations, or by a curvilinear motion $\vec{r}(t)$, then

$$K(t) = \frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|^3} = \frac{\|\vec{v}(t) \times \vec{a}(t)\|}{\|\vec{v}(t)\|^3}.$$

Remarks: a.) Formula (2) is useful even if the curve is 2-D. Just set the z -component to zero.

b.) If you know $a_N(t)$ already, then $K(t)$ is easy to compute using formula (2).

c.) The primes in (1) denote differentiation with respect to x . In (2) (and also in the remaining formulas on this sheet), the primes denote differentiation with respect to t .

Tangential Component of Acceleration:

1.) If you already know what $\vec{T}(t)$ is, then it's probably easier to use

$$a_T(t) = \vec{r}''(t) \cdot \vec{T}(t) = \vec{a}(t) \cdot \vec{T}(t).$$

2.) You can also use the formula

$$a_T(t) = \frac{d}{dt} \|\vec{r}'(t)\| = \frac{d}{dt} \|\vec{v}(t)\|.$$

Normal Component of Acceleration:

1.) If you computed $a_T(t)$ first, it's easier to use the Pythagorean identity,

$$\|\vec{a}(t)\|^2 = a_T^2(t) + a_N^2(t),$$

and then solve for $a_N(t)$.

2.) Otherwise, you can use

$$a_N(t) = \frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|} = \frac{\|\vec{v}(t) \times \vec{a}(t)\|}{\|\vec{v}(t)\|} = \|\vec{a}(t) \times \vec{T}(t)\|.$$

Remark: If you know $K(t)$ already, then $a_N(t)$ is easy to compute using formula (2).

Unit Normal Vector:

1.) If you know $a_T(t)$ and $a_N(t)$ already, then it is easier to use the tangential and normal decomposition formula for acceleration,

$$\vec{a}(t) = a_T(t)\vec{T}(t) + a_N(t)\vec{N}(t),$$

then solve for $\vec{N}(t)$.

2.) Otherwise, you can use

$$\vec{N}(t) = \frac{\vec{T}'(t)}{\|\vec{T}'(t)\|}.$$

Binormal Vector:

$$\vec{B}(t) = \vec{T}(t) \times \vec{N}(t).$$